JST-NSF-DFG-RCN Workshop on Distributed Energy Management Systems April 20-22, 2015

# Towards Harmonized Power System Control under Photovoltaic Power Prediction Uncertainty

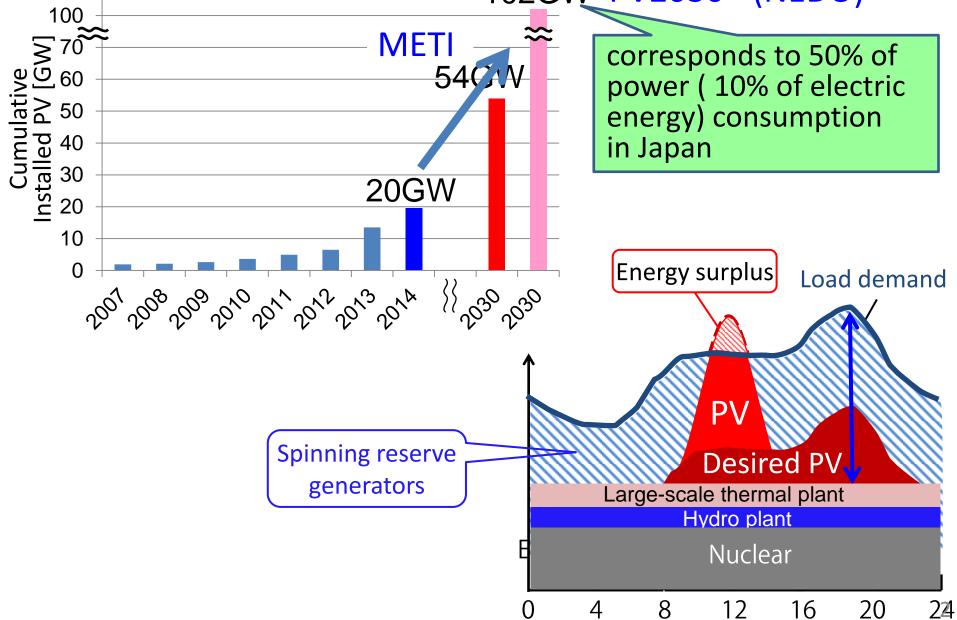
## Jun-ichi Imura

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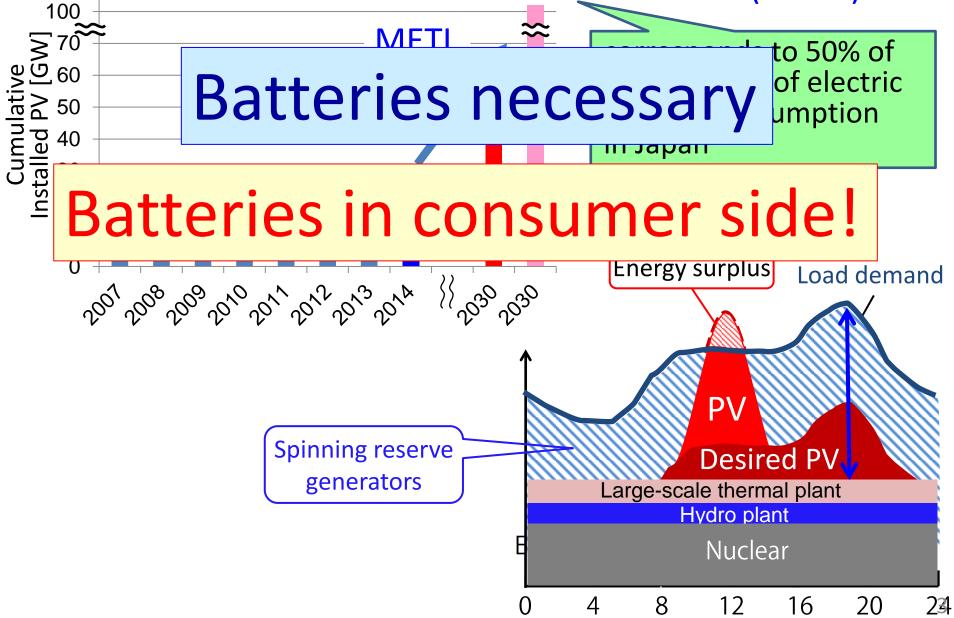
### **Installed PV Capacity in Japan**

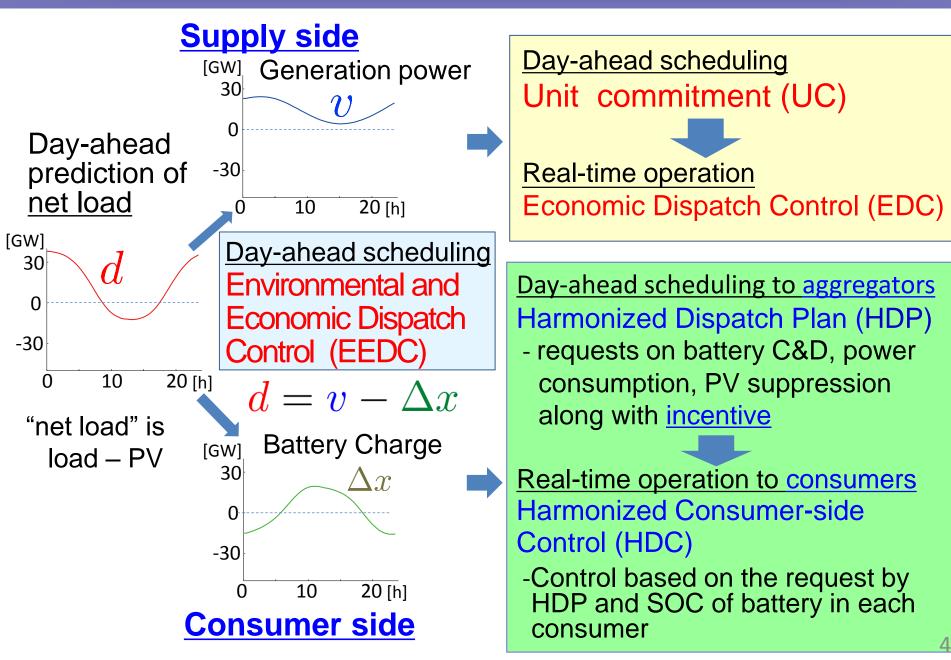
### 102GW PV2030+ (NEDO)

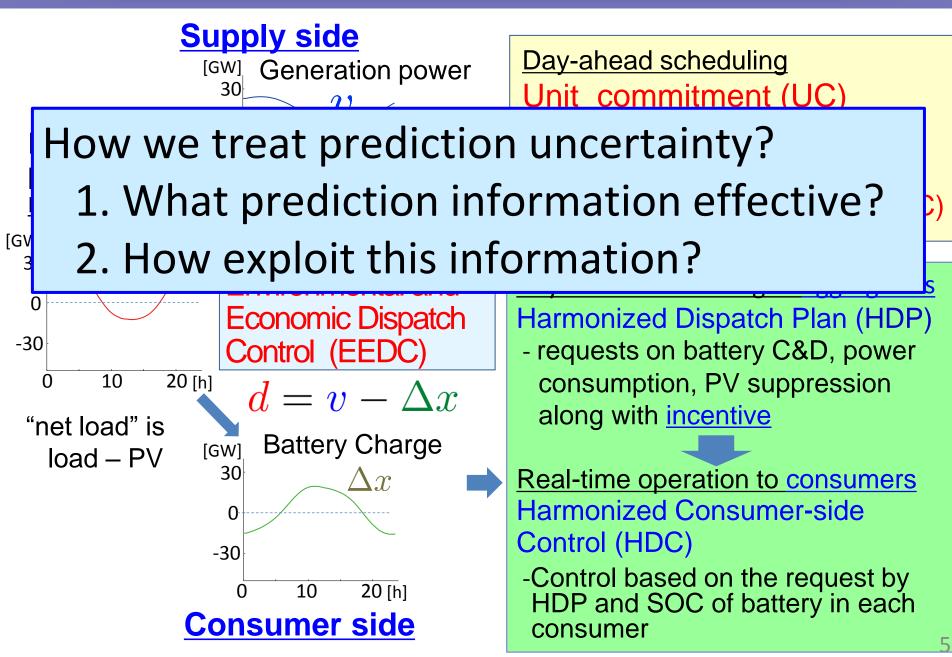


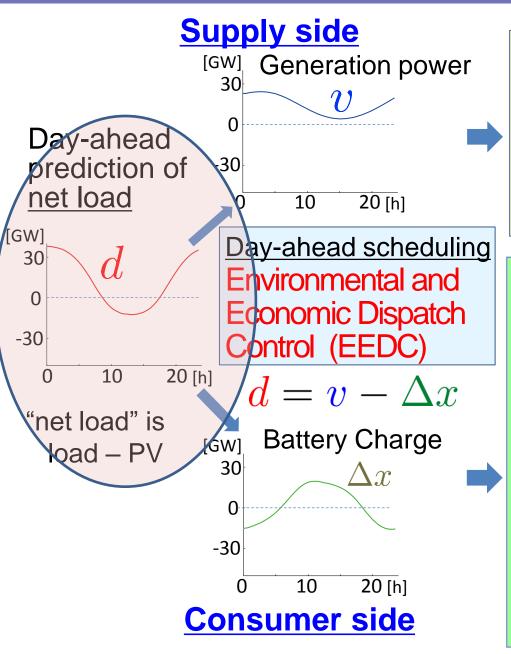
## **Installed PV Capacity in Japan**

102GW\_PV2030+ (NEDO)









Day-ahead scheduling Unit commitment (UC)

Real-time operation Economic Dispatch Control (EDC)

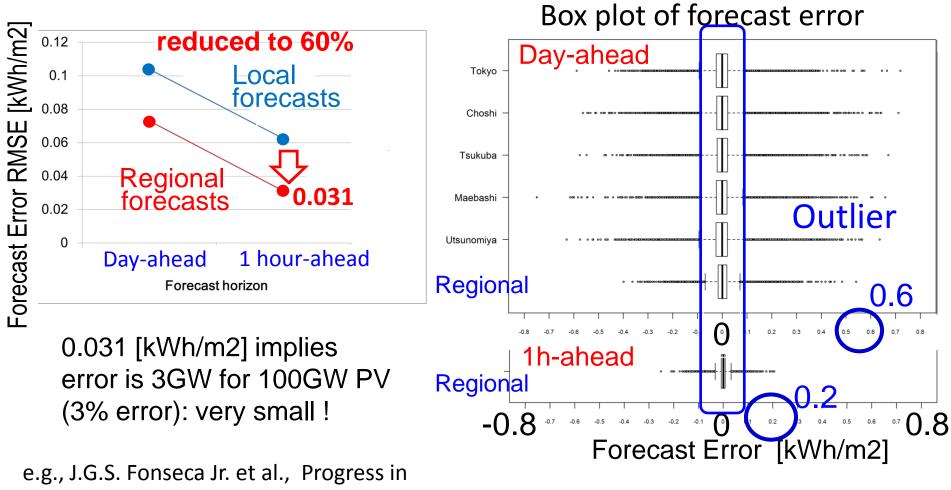
Day-ahead scheduling to aggregators Harmonized Dispatch Plan (HDP) - requests on battery C&D, power consumption, PV suppression along with incentive

Real-time operation to consumers Harmonized Consumer-side Control (HDC)

-Control based on the request by HDP and SOC of battery in each consumer

## **Forecast Error Evaluation**

Numerical weather prediction based machine learning method by Ozeki Group



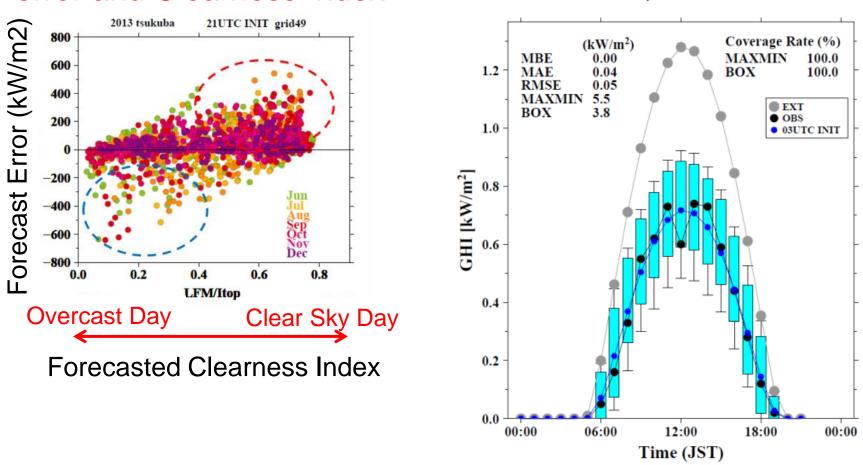
Photovoltaics Research and Applications 2014

## **Prediction Interval of PV Power Generation**

### Relation between Forecast error and Clearness Index

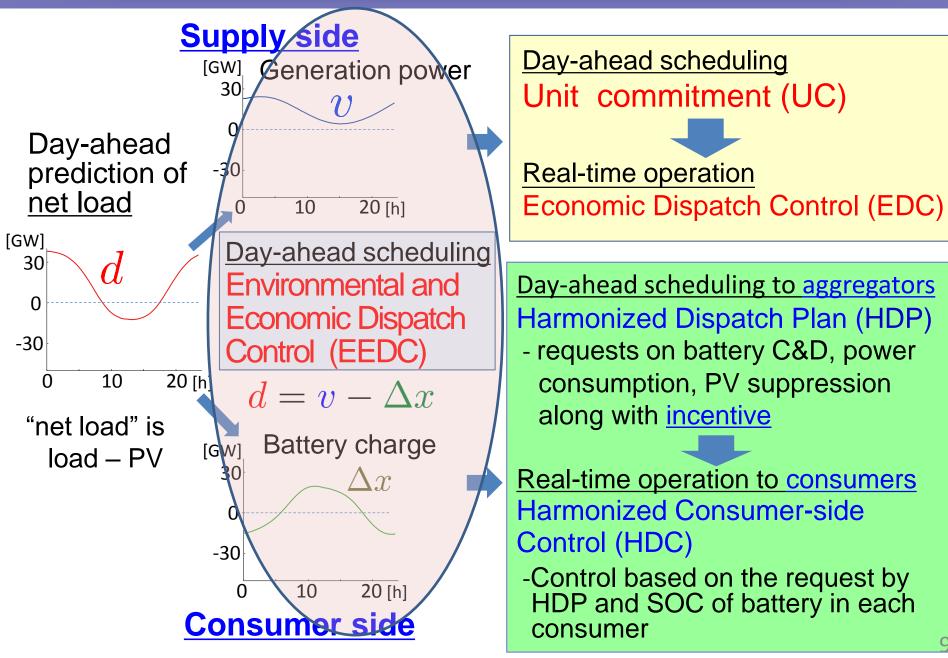
### Prediction interval with confidence

tokyoden 100716

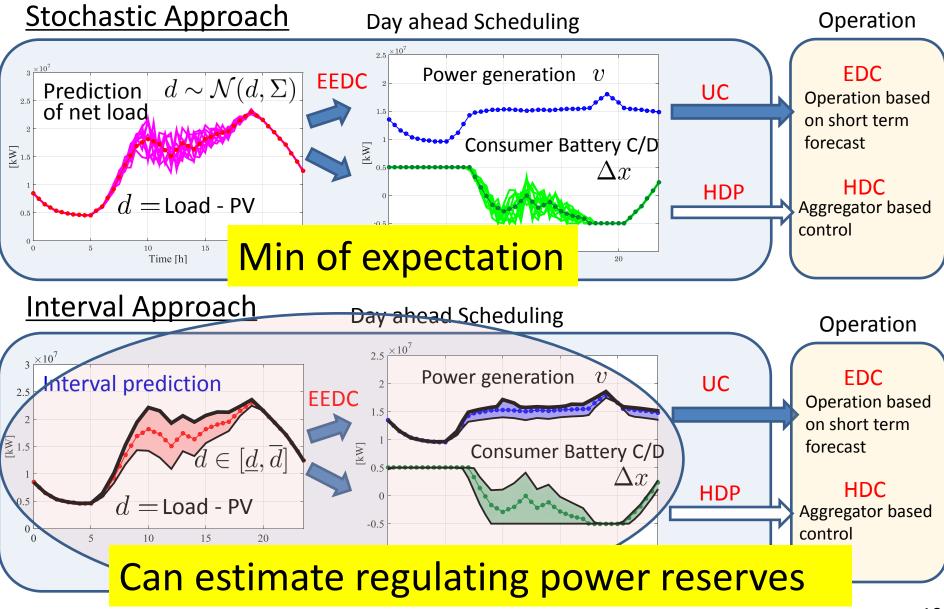


EXT: Extraterrestrial insolation

e.g., H. Ohtake et al., Energy Procedia, Vol. 59, pp.278-284, 2014



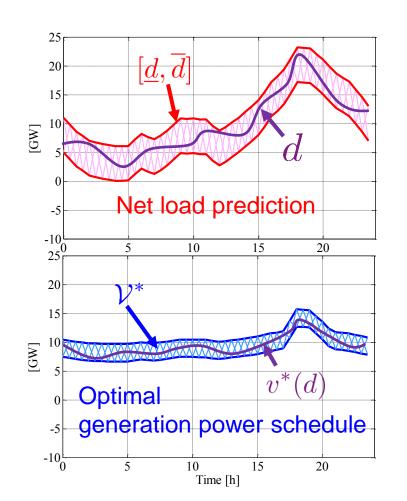
# **Stochastic Approach & Interval Approach**



## **Problem Formulation**

Given an interval  $[\underline{d}, \overline{d}] \subseteq \mathbb{R}^T$ . Find  $\mathcal{V}^* := \{v^*(d) | d \in [\underline{d}, \overline{d}]\}$ 

 $d := \begin{bmatrix} d(1) \\ d(2) \\ \vdots \\ d(T) \end{bmatrix}$ 



[Problem]

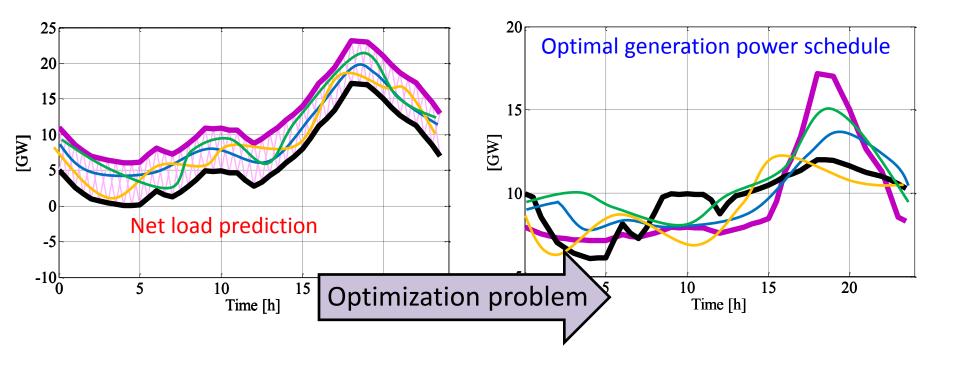
$$v^{*}(d) = \arg \min_{v} J(v)$$
Cost function
$$J(v) = \sum_{k=1}^{T} \{f(v(k)) + g(\Delta x^{\text{out}}(k))\}$$

$$k = 1 \text{ Fuel cost Battery deterioration cost}$$
s.t.
$$x(k+1) = x(k) + \alpha \Delta x^{\text{in}} - \frac{1}{\beta} \Delta x^{\text{out}}$$
Battery stored energy
$$d(k) = v(k) - (\Delta x^{\text{in}}(k) - \Delta x^{\text{out}}(k))$$
Net load
$$\Delta x^{a}_{\min} \leq \Delta x^{a}(k) \leq \Delta x^{a}_{\max} \ a \in \{\text{in, out}\}$$

$$x_{\min} \leq x(k) \leq x_{\max}$$

$$x(0) = x(T) \text{ To use battery sustainably}$$

# **Interval Approach to Worst Case Scenario**

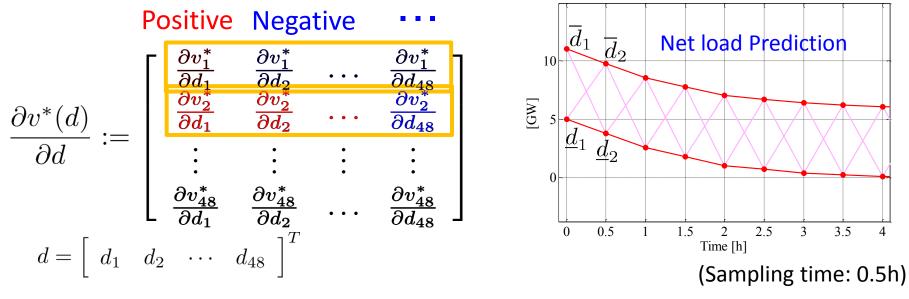


### Infinite number of trials may be required !

Hard to obtain the bounds of possible solutions for all net load predictions!

## **Monotonicity Based Approach**

#### For example •••



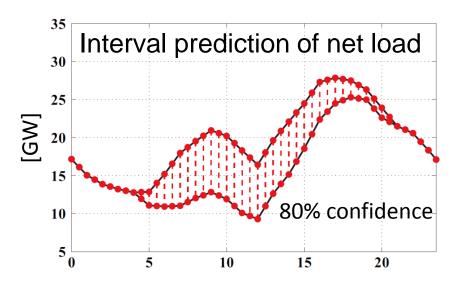
 $v_1^*(\underline{d}_1, \overline{d}_2, \dots, \overline{d}_{48}) \le v_1^*(d) \le v_1^*(\overline{d}_1, \underline{d}_2, \dots, \underline{d}_{48})$  $v_2^*(\underline{d}_1, \underline{d}_2, \dots, \overline{d}_{48}) \le v_2^*(d) \le v_2^*(\overline{d}_1, \overline{d}_2, \dots, \underline{d}_{48})$  $48 \times 2 \text{ number of trials}$ 

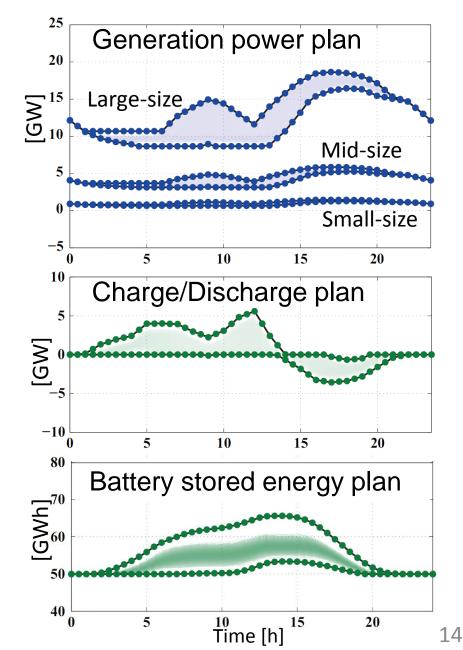
- can find the bounds of possible optimal solutions by finite trials
- can prove that the optimization problem is monotone w.r.t d (the sign is constant)

e.g., T. Ishizaki et al., Proc. of MTNS14, pp.792-799, 2014

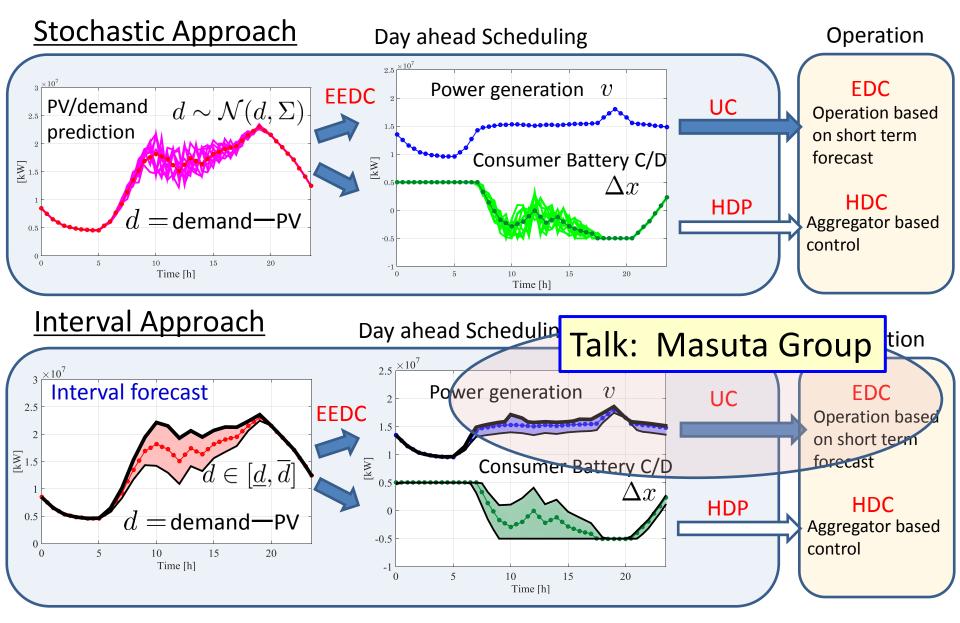
## **Simulation**

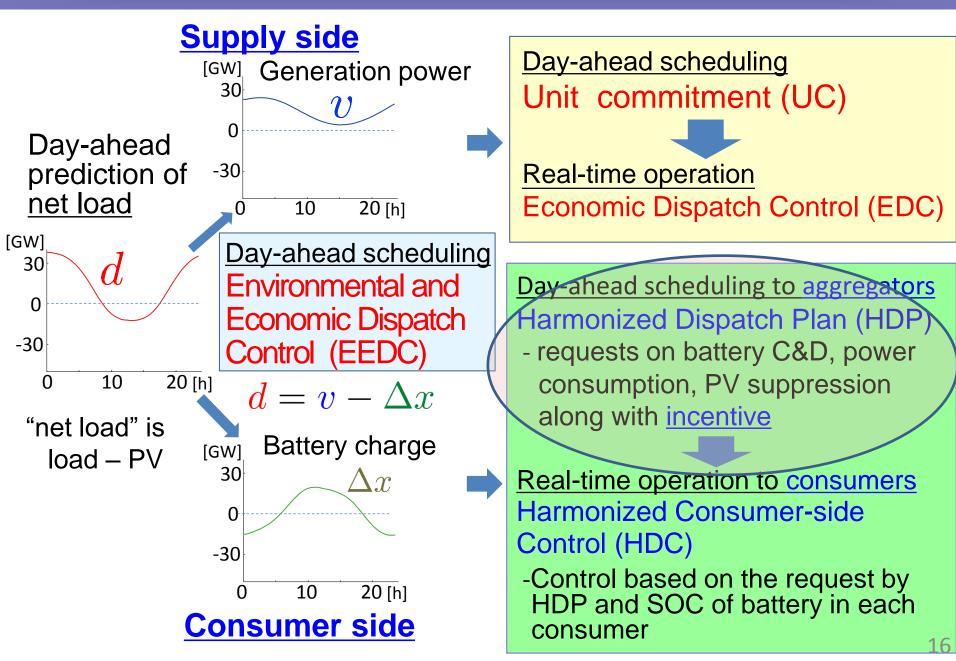
| Area to be controlled                     | Tokyo (19million) |
|---|-------------------|
| Load (max)                                | 48[GW]            |
| Installed PV (max)                        | 23[GW] (26%)      |
| Inverter capacity of<br>installed Battery | ±10[GW] (15%)     |
| Installed Battery (max)                   | 80[GWh] (15%)     |
| C/D efficiency                            | 0.9 for both      |





# **Stochastic Approach vs Interval Approach**





## HDP (Harmonized Dispatch Plan)

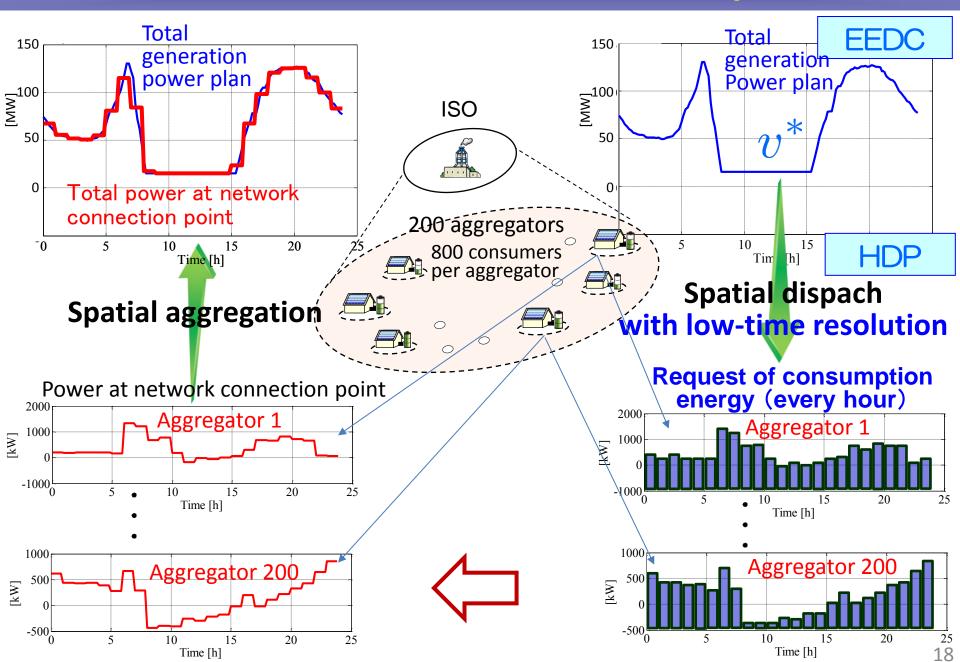
Entire system: 
$$d(t) = v(t) - \Delta x(t)$$
  
Aggregator  $i: d_i(t) = \underbrace{v_i(t)}_{N} - \underbrace{\Delta x_i(t)}_{Charge power of battery}_{Power at NW connection point (consumption power)}$   
Problem of finding requests to Aggregators  
Given  $v^*(t)$  and  $d_i(t)$ ,  $i = 1, \dots, N$ ,  
find  $v_i(t)$ ,  $i = 1, \dots, N$  such that  $\sum_{i=1}^{N} v_i(t) \simeq v^*(t)$   
s.t. constraints on battery capacity etc.  
How should we deal with prediction uncertainty ?

Consider low-time-resolved requests !

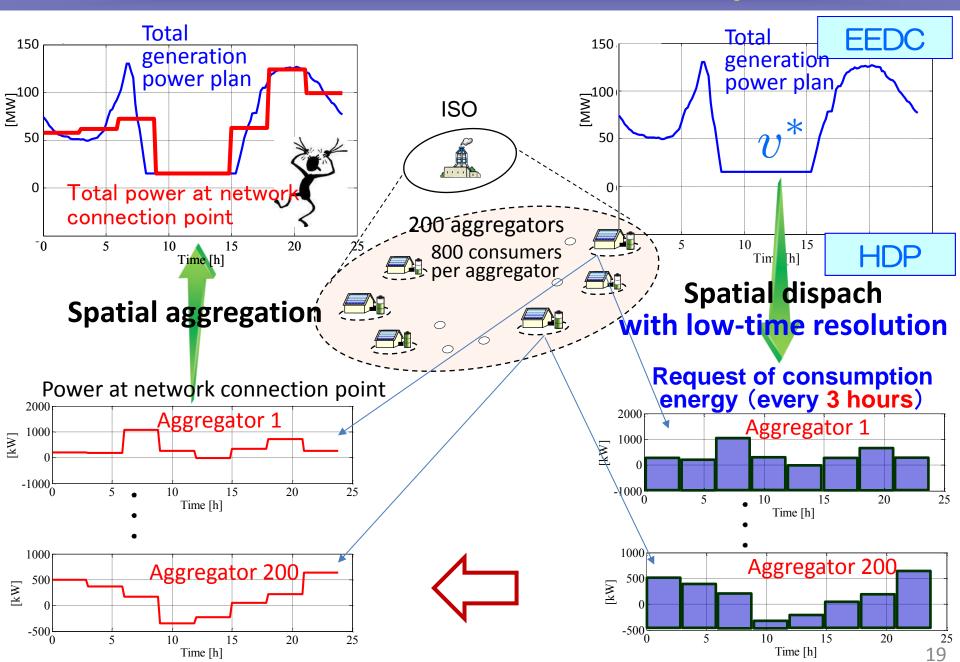
- Prediction uncertainty is reduced
- Constraints are relaxed
- Flexibility of consumers is increased

e.g., T. Sadamoto, et al., IEEE Trans on Smart Grid, 6-2, 853-865, 2015

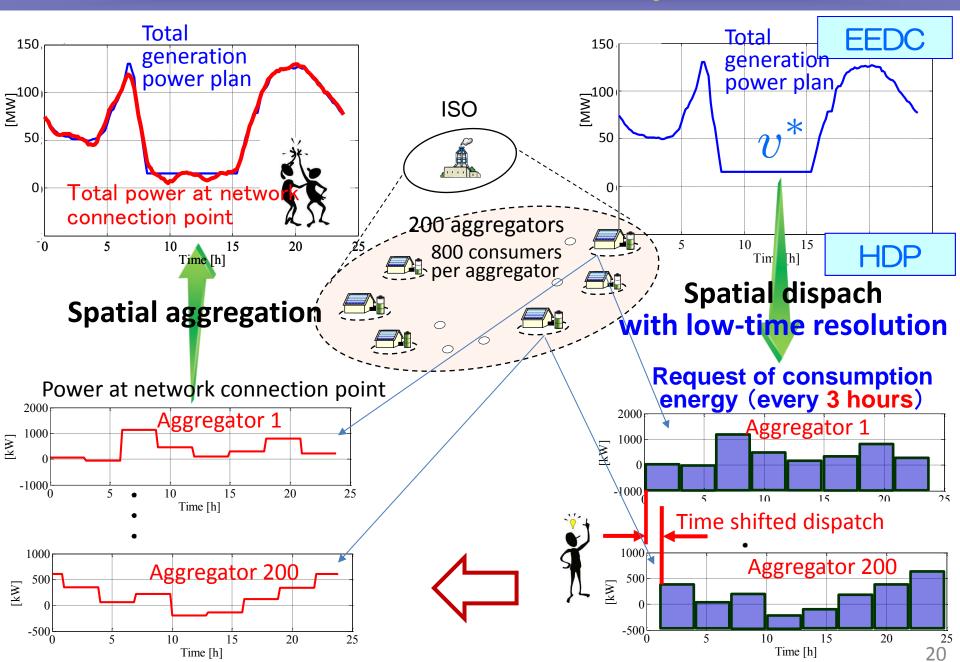
### **HDP: Low-time Resolution Request**



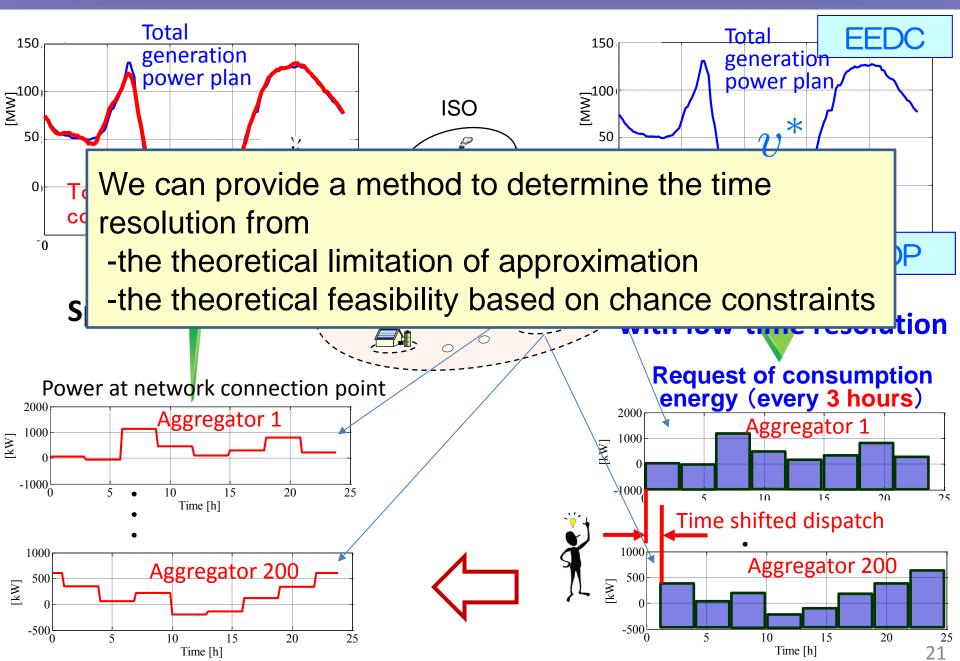
### **HDP: Low-time Resolution Request**

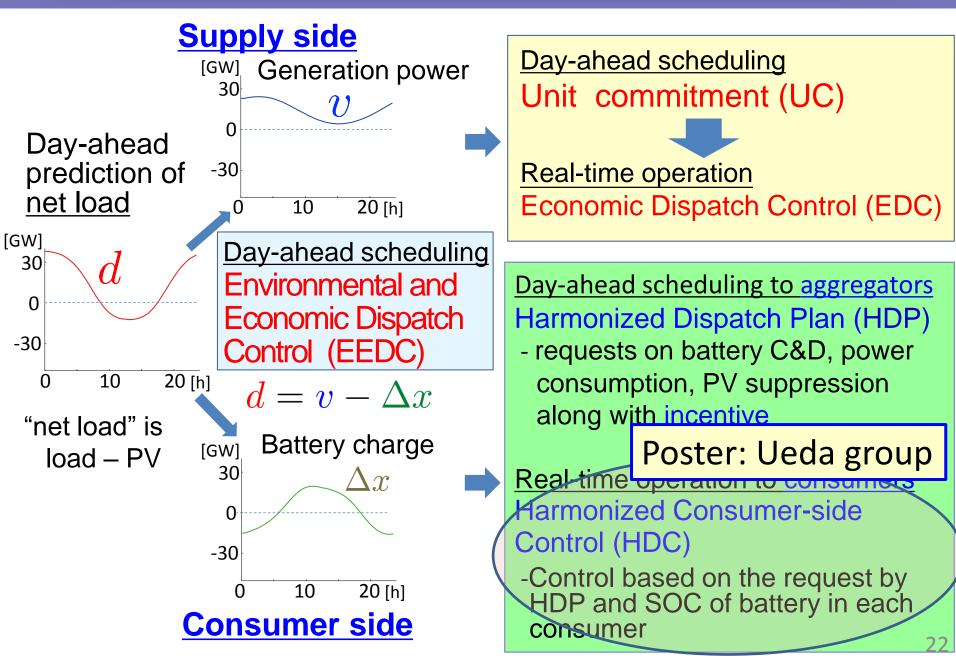


### **HDP: Time Shifted Request**



## **HDP: Time Shifted Request**





## **JST CREST Past Project Team**

 Project title: Optimal Dispatch Control of Huge-Scale Power Systems under Prediction Uncertainty of Photovoltaic Power Generation
 Term: October 2013 – March 2015 (2.5 years)
 PI: Jun-ichi Imura (Tokyo Institute of Technology)

4 Group leaders (17 researchers)



Jun-ichi Imura (Tokyo Tech)



Yuzuru Ueda (Tokyo U of Science)



Taisuke Masuta (The Institute of Applied Energy)



Taisuke Masuta (Advanced Industrial Science and Technology)

**Systems and Control** 

#### Power Systems Engineering

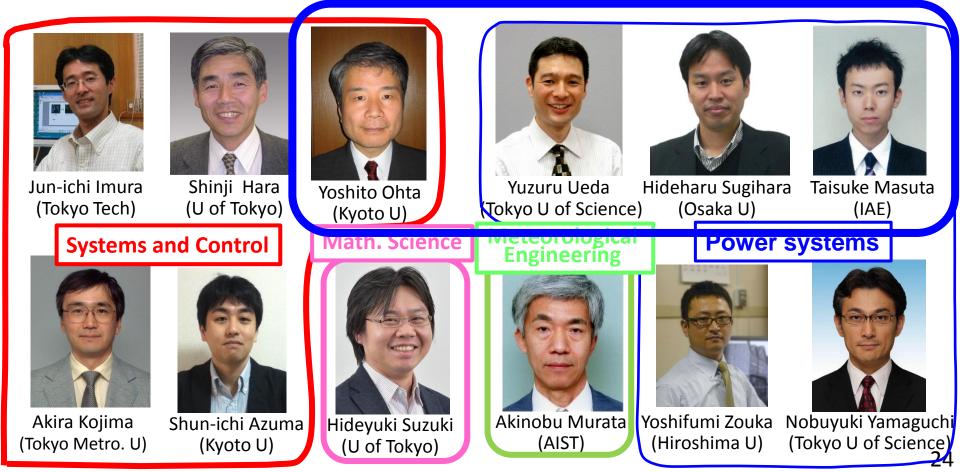
Meteorological Engineering

## **JST CREST Renewed Project Team**

Project title: System Theory for Harmonized Power System Control Based on Photovoltaic Power Prediction Term: April 2015 – March 2020 (5 years)

PI: Jun-ichi Imura (Tokyo Institute of Technology)

### 12 Group leaders (59 researchers in total ):



## **Project Research Topics**

Target: System Theory for Harmonized Power System Control Based on Photovoltaic Power Prediction

PV-prediction based, Spatiotemporally Cooperative Power System Control

- To deal with prediction uncertainty with heavy-tail distribution, need stronger ST-cooperation of various controls such as EEDC,UC,EDC,LFC,GF,DR,HDP,HDC,.... including control of transmission/distribution networks
- Collaboration room with digital power system simulator

Structure Design of Power System including Mid-layer

- Roles of mid-layer including aggregators
- Markets points of view