



Faculty Research Overview

CURENT Annual Industry Conference

April 29 and May 1, 2024

Knoxville, TN



Northeastern



Rensselaer

TUSKEGEE



Fangxing “Fran” Li

- UTK John W. Fisher Professor, CURENT Director, LTB Lead
- Research Interests: resilience, demand response, power system economics, machine learning for power.
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2023-24 Research Projects/Highlights

1. CURENT Large-scale testbed (LTB)
2. Development of Load Flexibility Valuation Methodology & Framework to Input into Planning Tools (**Southern Company**)
3. Networked Microgrids and Solid-State Power Substations Hierarchical Systems Frameworks (**ORNL**)
4. Production Cost Modeling to Assess the Benefit of Geothermal Deployment (**ORNL**)
5. Model-Free Adaptive Control (MFAC) for Autonomous and Resilient Microgrids (**DOD ESTCP**)
6. Adaptive dynamic coordination of damping controllers through deep reinforcement and transfer learning (**NSF**, PI: H. Pulgar)
7. An Equitable, Affordable & Resilient Nationwide Energy System Transition (EARNEST) (**DOE/Stanford**)
8. POSE: Phase I: Toward an Open-Source Ecosystem for Power Systems Research, Education, and Industry Applications (**NSF/Oklahoma State University**)

CURRENT Large-scale Testbed (LTB)



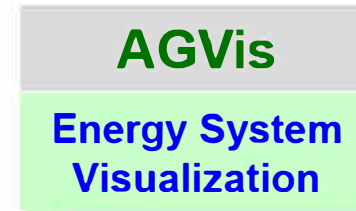
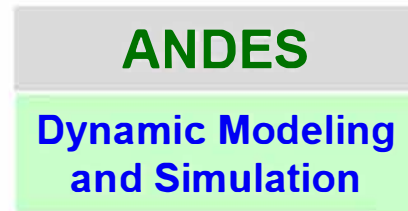
Project Objectives

- To develop a **closed-loop platform** that includes both dynamic and dispatch/market simulation
- To enable **dispatch-dynamic interfaced co-simulation**

Recent Achievements

- Created [Homepage](#) for CURENT LTB
- Created [Linkedin Account](#) for CURENT LTB
- AMS development, benchmark, and release
- AGVis backend improvement with web application

Hybrid symbolic-numeric power system modeling and simulation

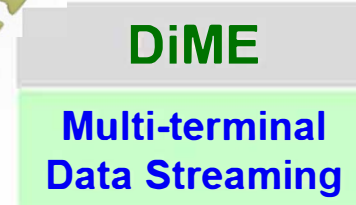
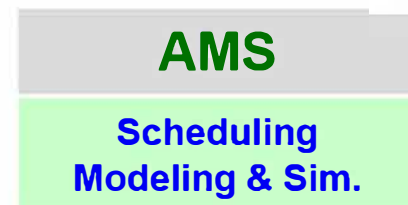


Geographical visualization for energy system



Best Graduate Paper Award, NAPS 2024

Dynamic information interfaced scheduling modeling and simulation



Data messaging between multiple power system components

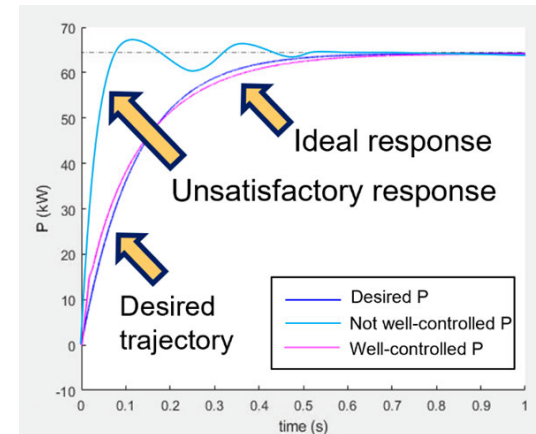
LTB Structure



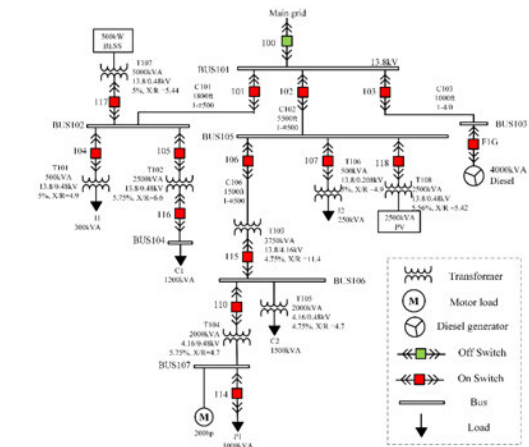
Model-Free Adaptive Control (MFAC) for Autonomous and Resilient Microgrids (1)

Project Objectives

- Employ domain knowledge and **AI** to achieve autonomous grid-following and grid-forming controls for microgrids
- Achieve higher grid resilience
- Microgrid control under insufficient capacity
- Virtual Inertia Scheduling



Power curve tracking the predefined trajectory

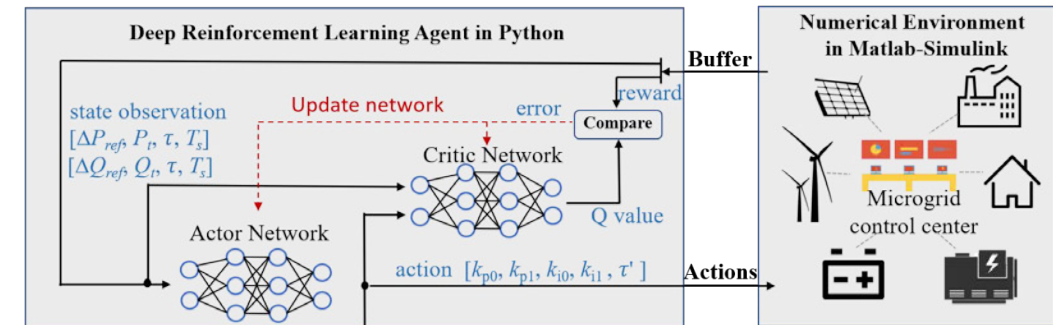


Modified Banshee microgrid in HTB

Recent Achievements — Part I:

PQ Control with trajectory tracking capability [1]

- Developed inverter PQ control for trajectory tracking using **physics-informed** deep reinforcement learning
- Configure modified Banshee microgrids in CURENT HTB and validate the controller through power HIL experiment



Offline training

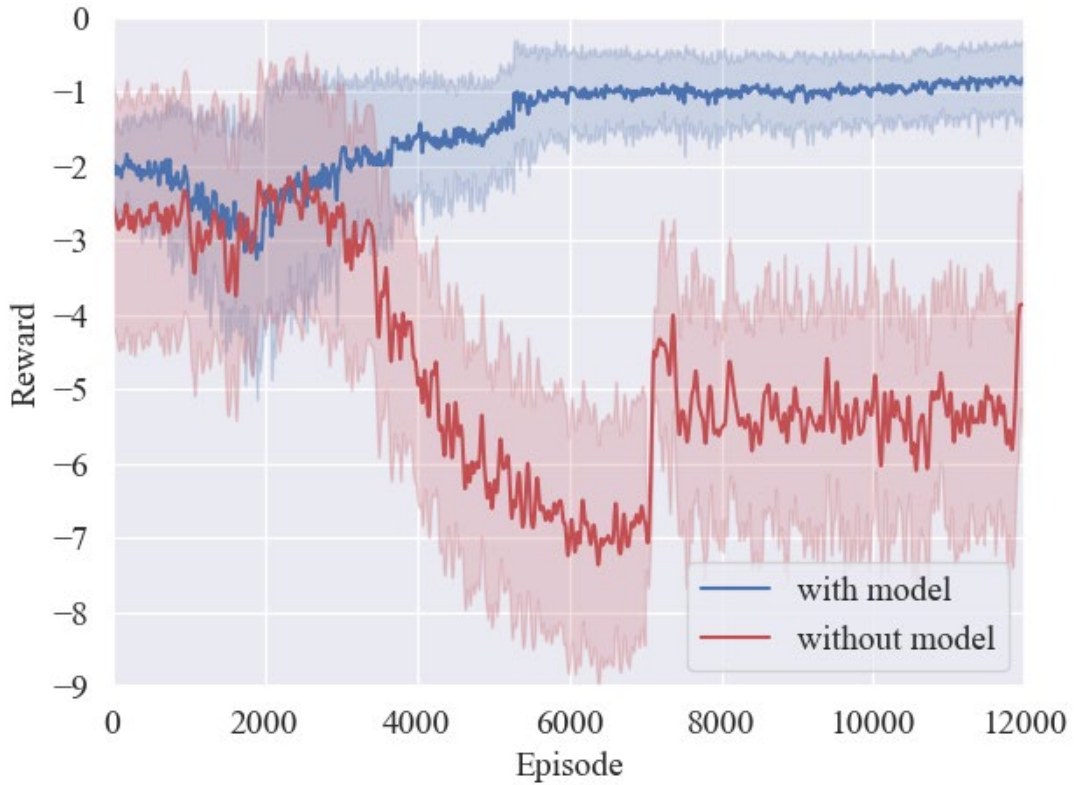
plus

Online demonstration

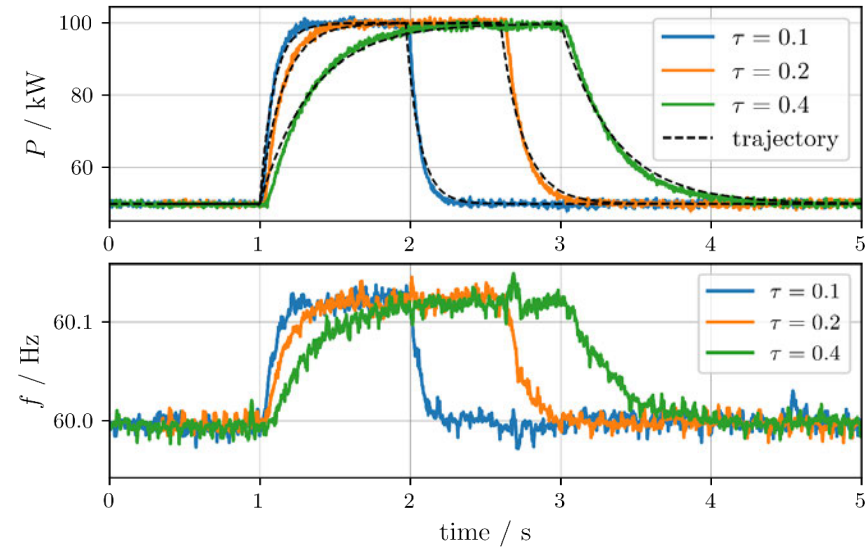


[1] B. She, F. Li*, et.al. "Inverter PQ Control with Trajectory Tracking Capability for Microgrids Based on Physics-informed Reinforcement Learning", *IEEE Transactions on Smart Grid*, 2024.

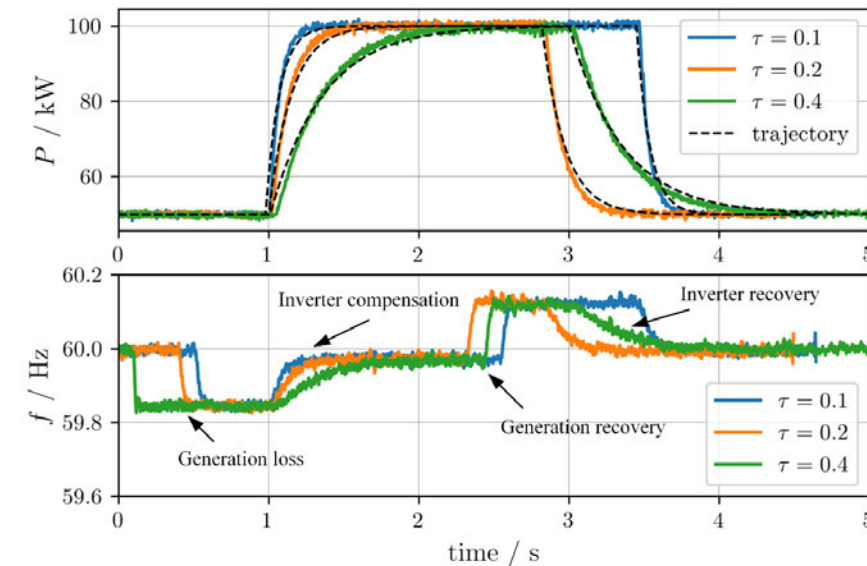
Results of PQ control with trajectory tracking



Reward curve with and without model-based analysis



Scheduling reference change



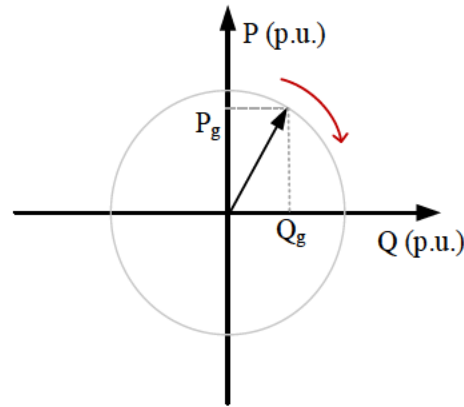
Generation reduction & recovery

Model-Free Adaptive Control (MFAC) for Autonomous and Resilient Microgrids (2)

Recent Achievements – Part II:

V-f Control considering DER inadequacy [2]

- Developed decentralized and coordinated V-f control under **insufficient** resource capacity for islanded microgrids
- Mathematically proved the existence of equilibriums and small signal stability



Grid-forming inverter output following the limited DER capacity

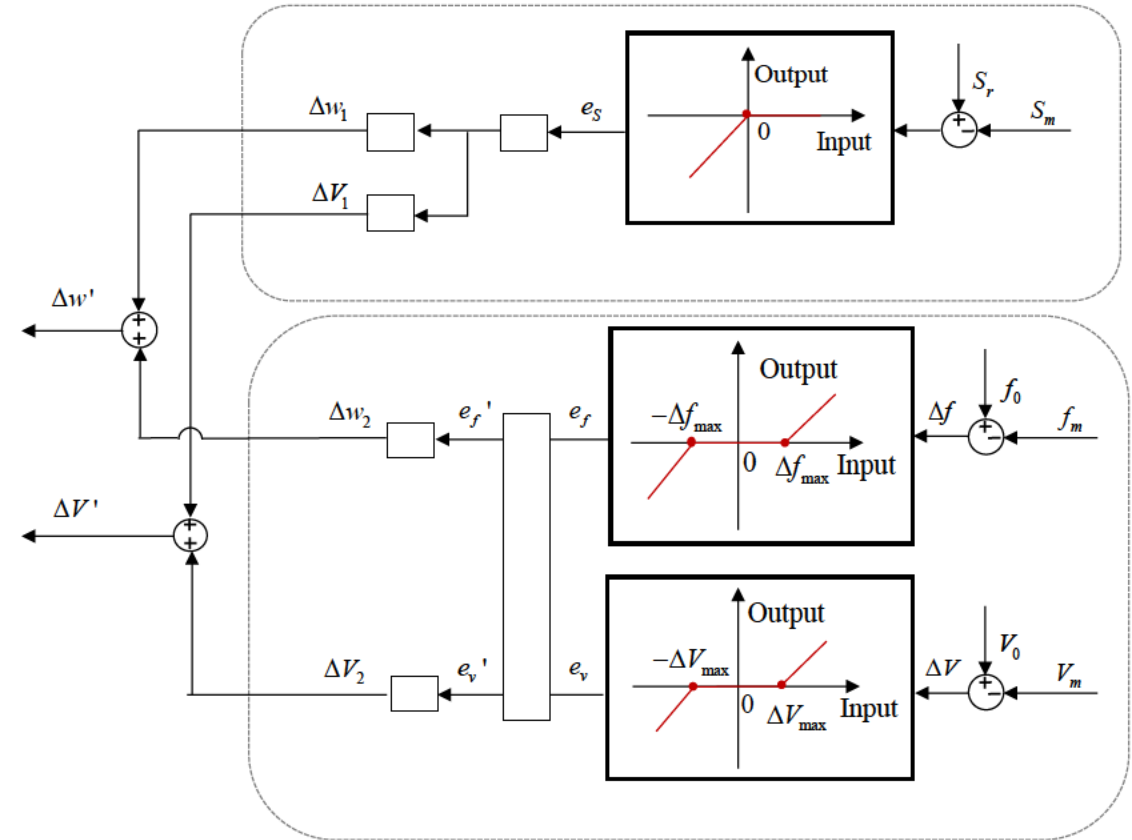
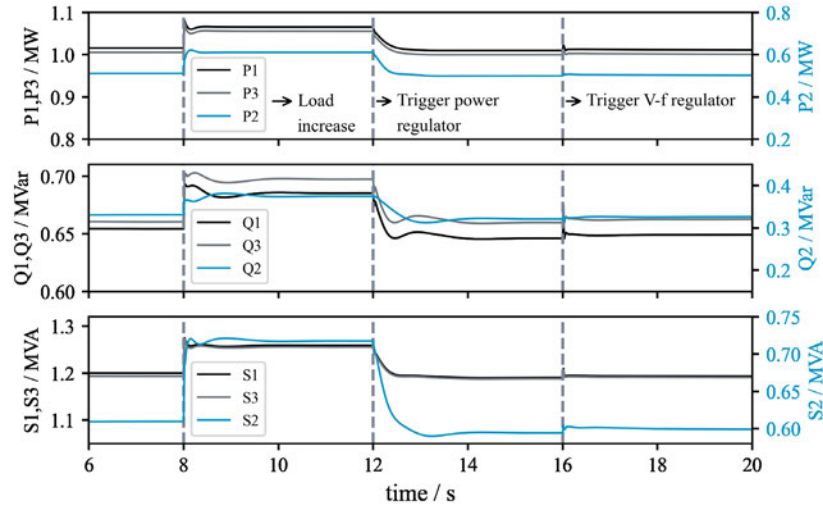


Diagram of the proposed decentralized and coordinated control framework

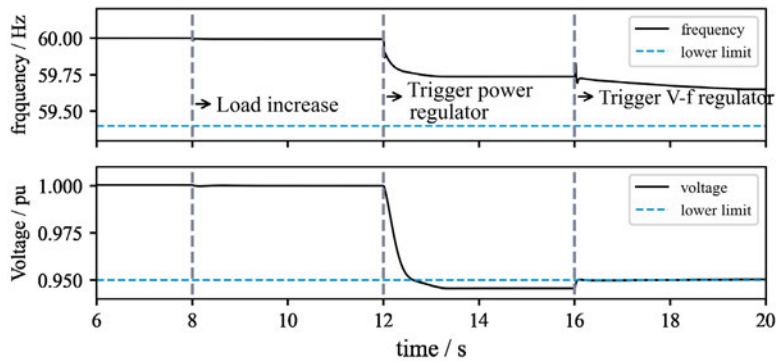
Results of V-f control with DER inadequacy



Simulation results: Scenario 1

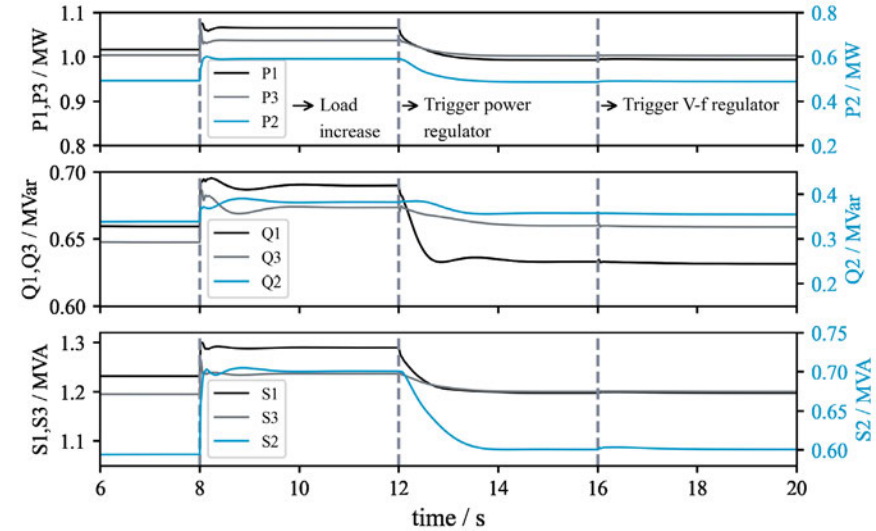


Dynamic inverter output

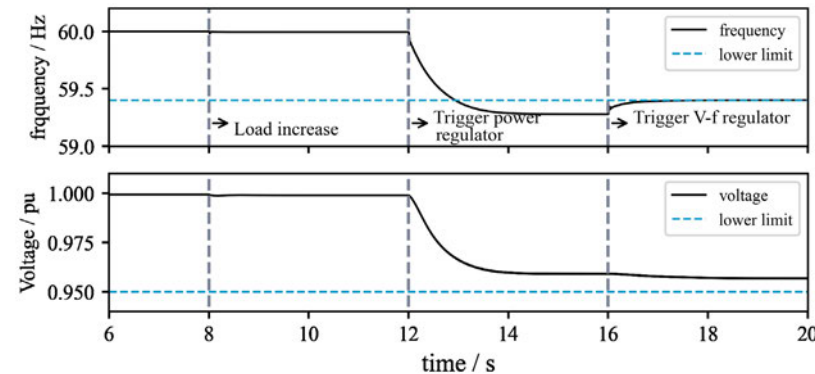


V-f response: increase Q, decrease P

Simulation results: Scenario 2



Dynamic inverter output



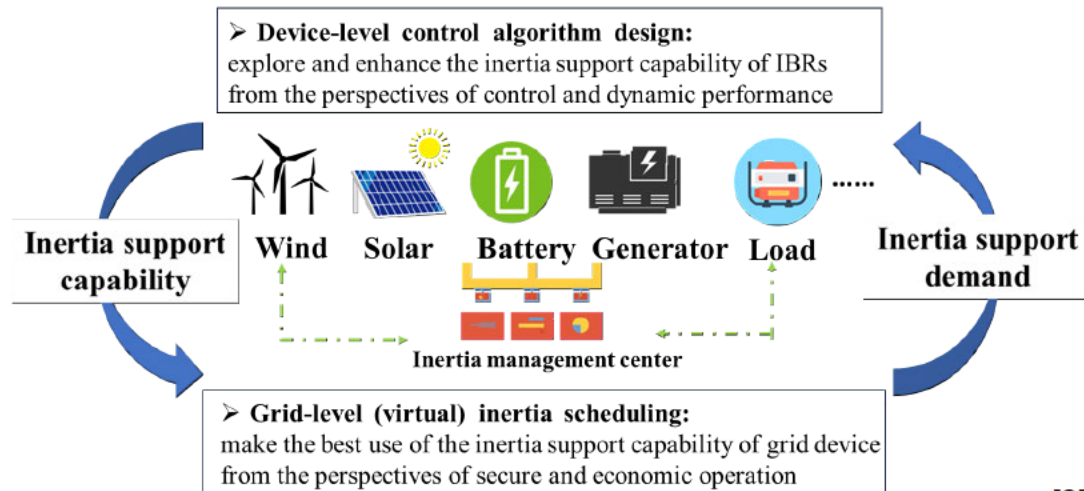
V-f response: increase P, decrease Q

Model-Free Adaptive Control (MFAC) for Autonomous and Resilient Microgrids (3)

Recent Achievements – Part III:

Virtual Inertia Scheduling (VIS) for low inertia grids [3]

- Proposed the concept of VIS, a security-constrained and economy-oriented inertia scheduling and generation dispatch framework for power grids with a large scale of IBRs.
- VIS schedules the power setting points, as well as the **control modes** and **control parameters** of IBRs to provide secure and cost-effective inertia support.



➤ Formulation of VIS

$$\min_{P, M, D} C_{gen}(P) + C_{aux}(P, M, D)$$

Inertia support cost

Generation cost

s.t. 1) Standard dispatch constraints

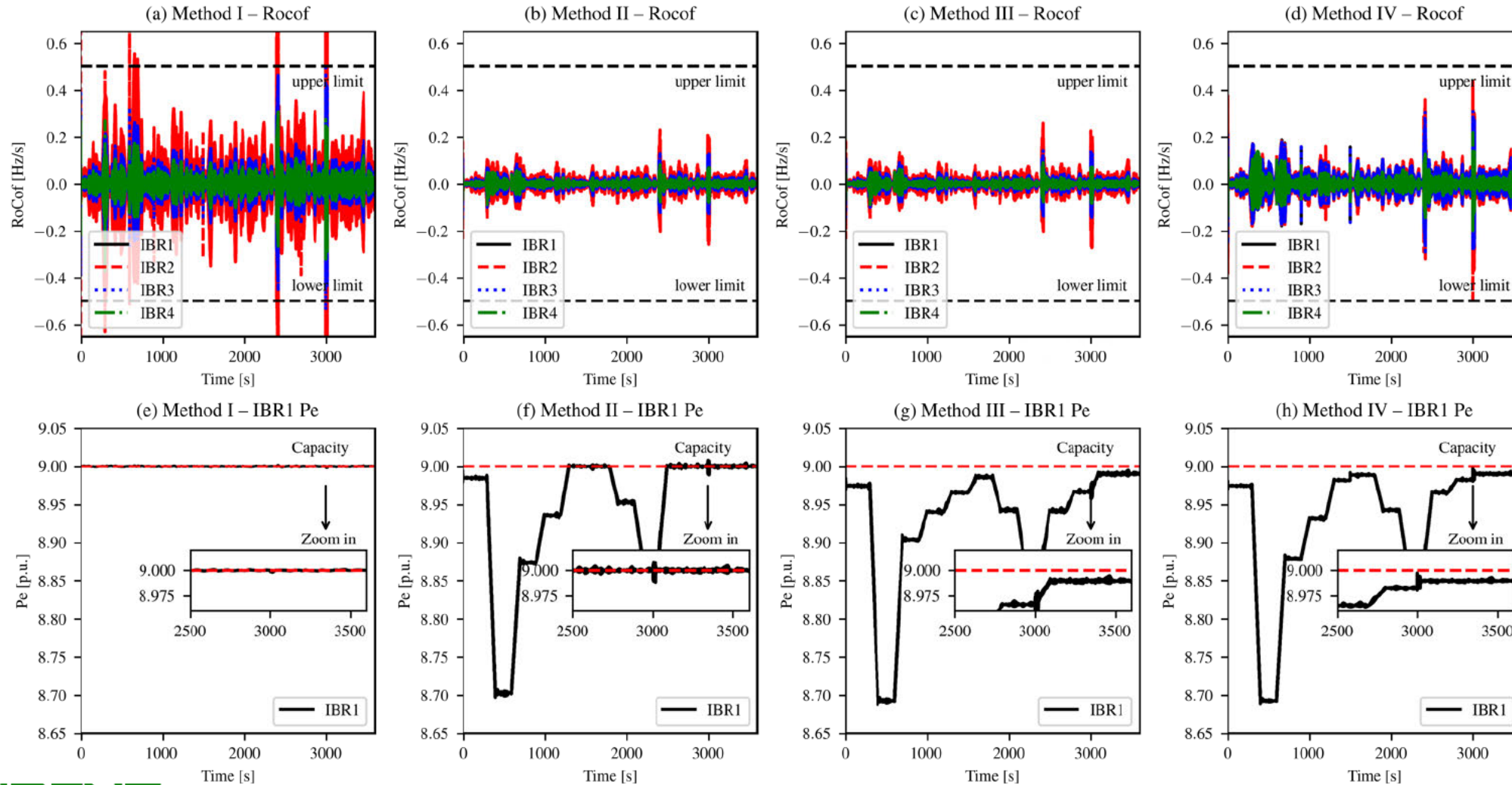
$$2) \begin{cases} M_i^{\min, ibr} \leq M_i^{ibr} \leq M_i^{\max, ibr}, \forall i \in \{1, \dots, N_{ibr}\} \\ D_i^{\min, ibr} \leq D_i^{ibr} \leq D_i^{\max, ibr}, \forall i \in \{1, \dots, N_{ibr}\} \end{cases}$$

$$3) \begin{cases} -RoCof_{lim} \leq f_0 \frac{\Delta P_{e,t}}{M_t} \leq RoCof_{lim}, \forall t \in \{1, \dots, T\} \\ f_{min} \leq f_0 + \Delta f_{nadir,t} \leq f_{max}, \forall t \in \{1, \dots, T\} \end{cases}$$

[3] B. She, F. Li*, et.al. "Virtual Inertia Scheduling for Power Systems with High Penetration of Inverter-based Resources". *IEEE Transaction on Sustainable Energy*, 2024.

Results of Virtual Inertia Scheduling (VIS)

➤ Comparison study of one-hour dispatch + time-domain simulation





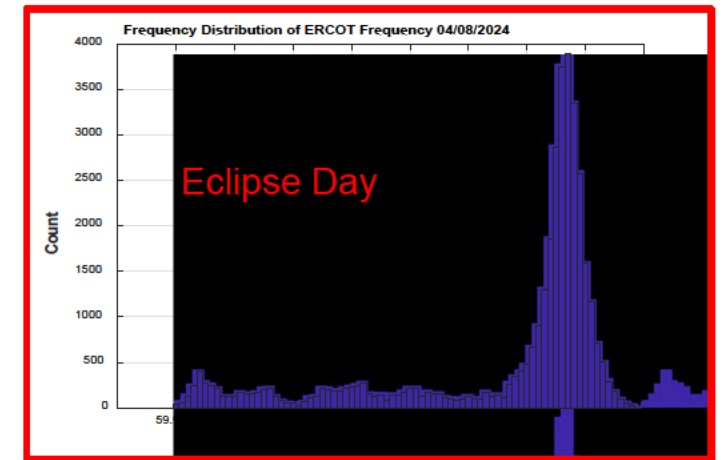
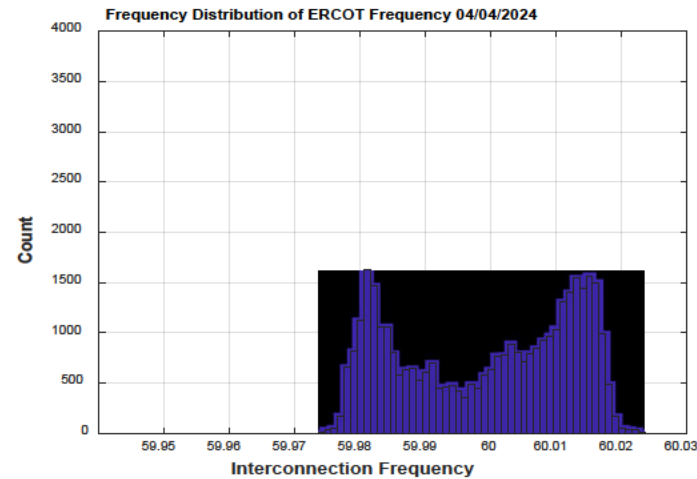
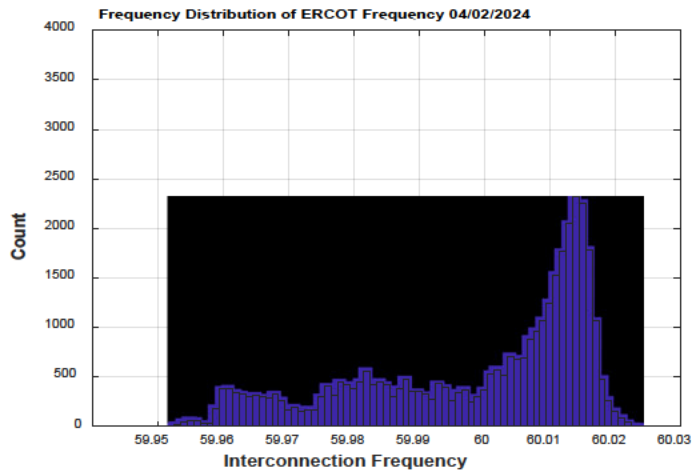
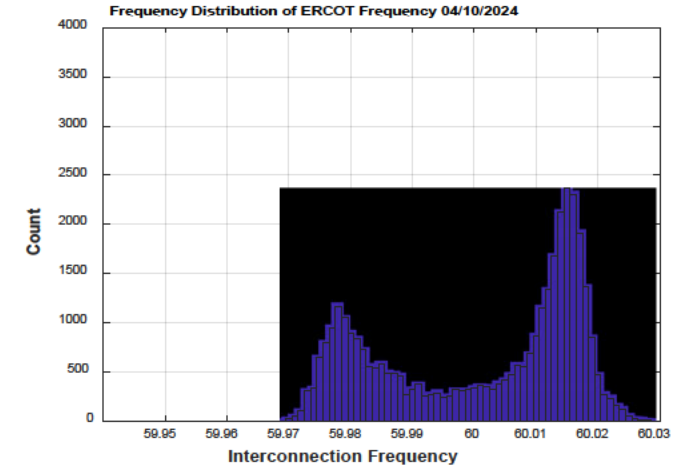
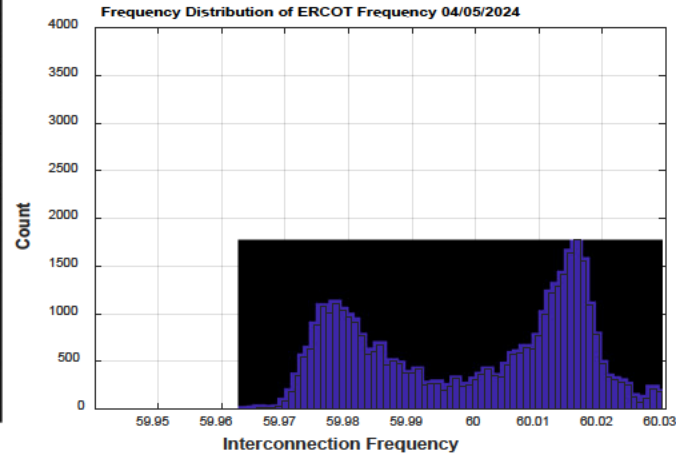
Yilu Liu

- **UT/ORNL Governor's Chair, CURENT Deputy Director**
- **Research Interests: grid monitoring and applications, oscillation damping control, Inertia and grid strength, EMP impact, Micro Grid,**
- **Liu@utk.edu 865 266 3597, powerit.utk.edu, fnetpublic.utk.edu**

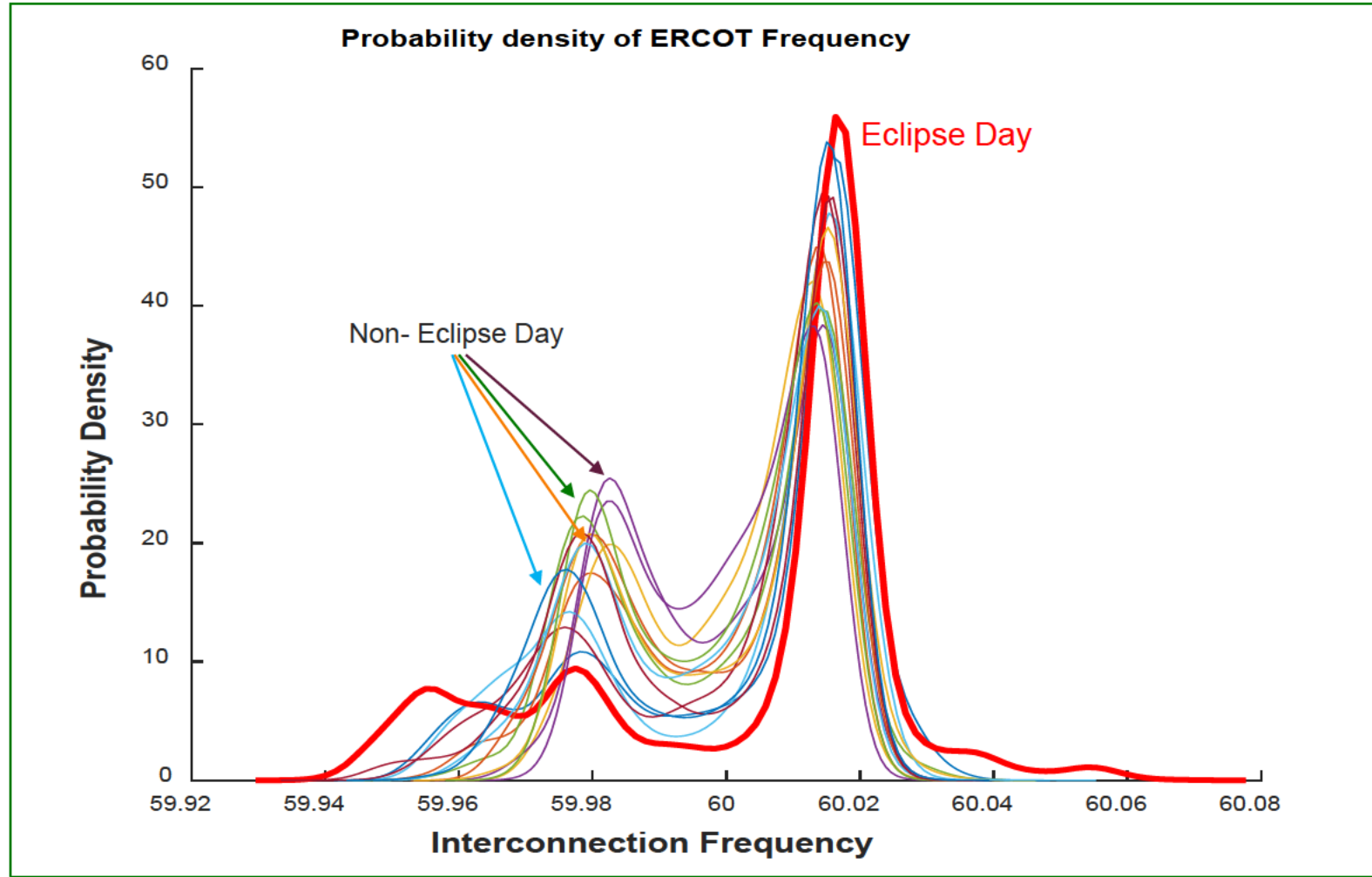
1. Forced oscillation source location tool (EPRI)
2. Forced oscillation source type classification (TVA)
3. EI system inertia trending study (Dominion)
4. Data center models (Dominion)
5. Digital twin for microgrid (Southern Company)
6. Adaptive oscillation damping control and field test (EPRI, NYPA, TERNA, DOE)
7. EMP susceptibility characterization of generation stations (ORNL, TVA, Dominion)
8. Secure timing system using pulsar signal (NSF)
9. BESS probing for inertia estimation in real time (NREL, KIUC, AES, GPTech)
11. Pump storage operation signature-based inertia estimation (WPTO, Dominion, TVA, PG&E)
12. Develop low cost syn-wave monitors for PV systems (ORNL, DiGiCollect).
13. OEDI Distribution state estimation, VW control, and transient data generation (ORNL, DOE SETO)
14. Virtual Operator Assistance – AI based fast real time transient stability prediction tool (ORNL, DOE AGM)
15. FNET/GridEye data transmission, visualization, and real time applications (NERC, AGM)
16. Oscillation and inertia trending (ORNL)
17. Landfill site microgrid development feasibility study (EPB, KUB)
18. Real time grid frequency prediction (Apple)

2023-2024 Research Projects

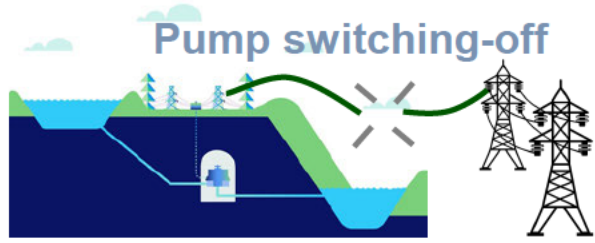
ERCOT Frequency - Eclipse Time 18:00 -19:00 UTC



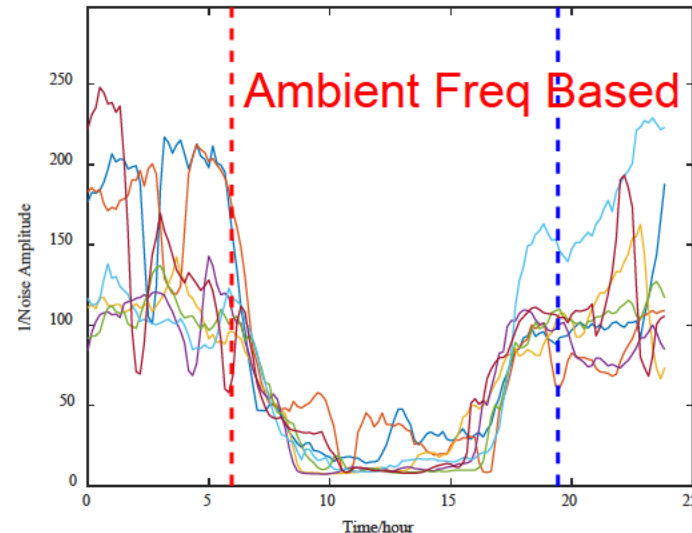
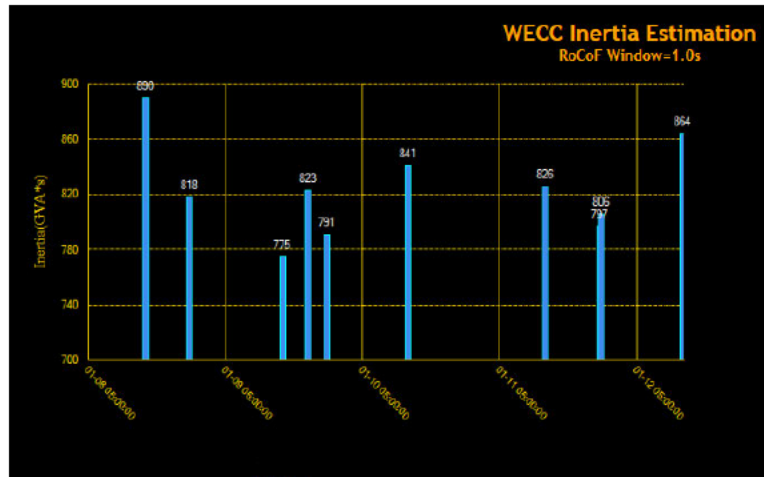
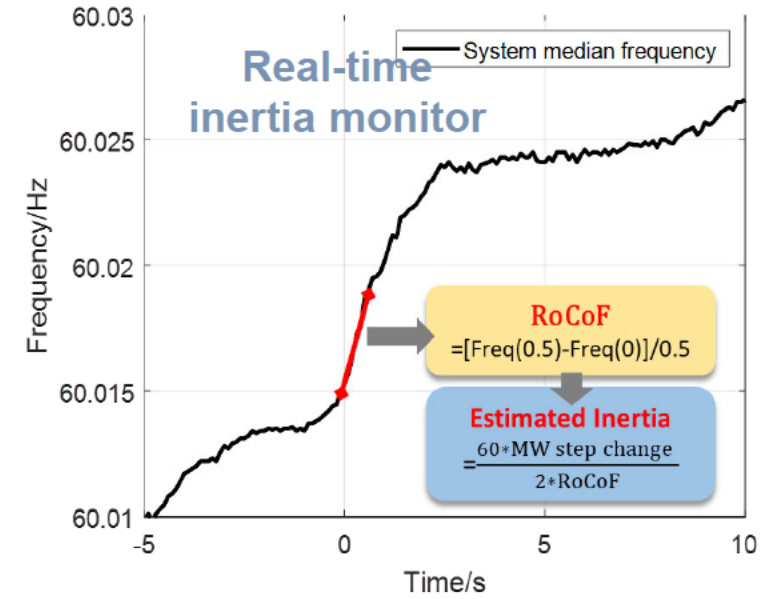
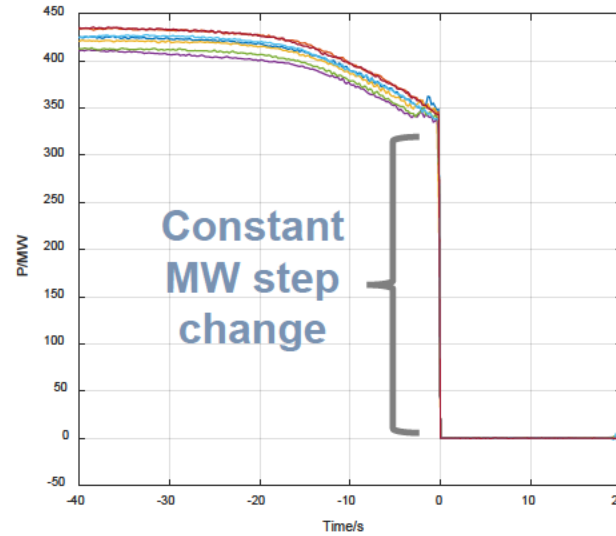
Probability Density of ERCOT (Eclipse hours)



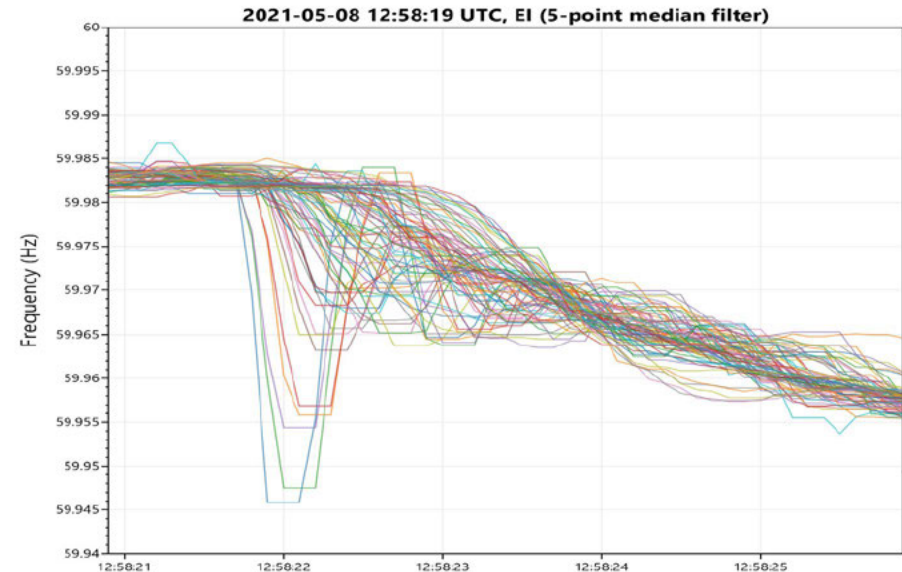
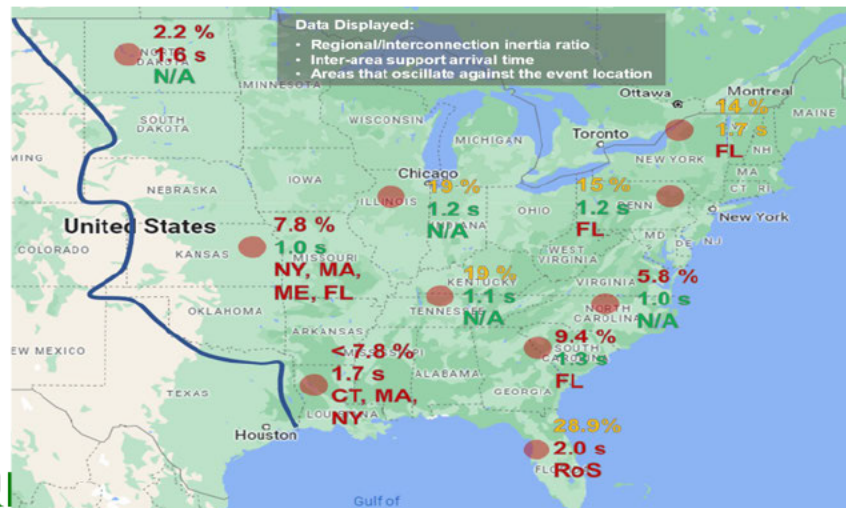
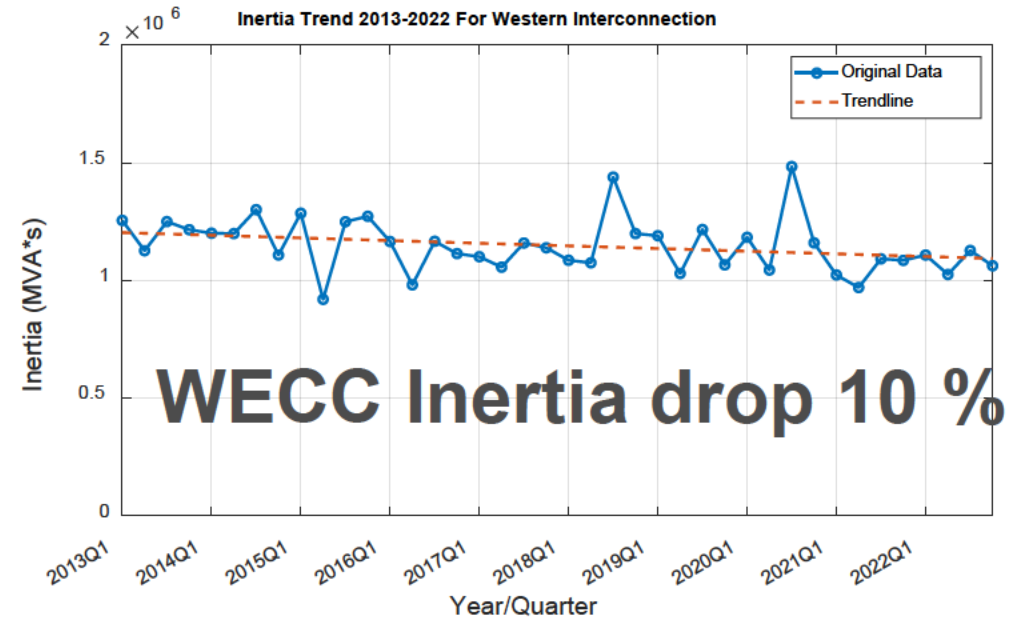
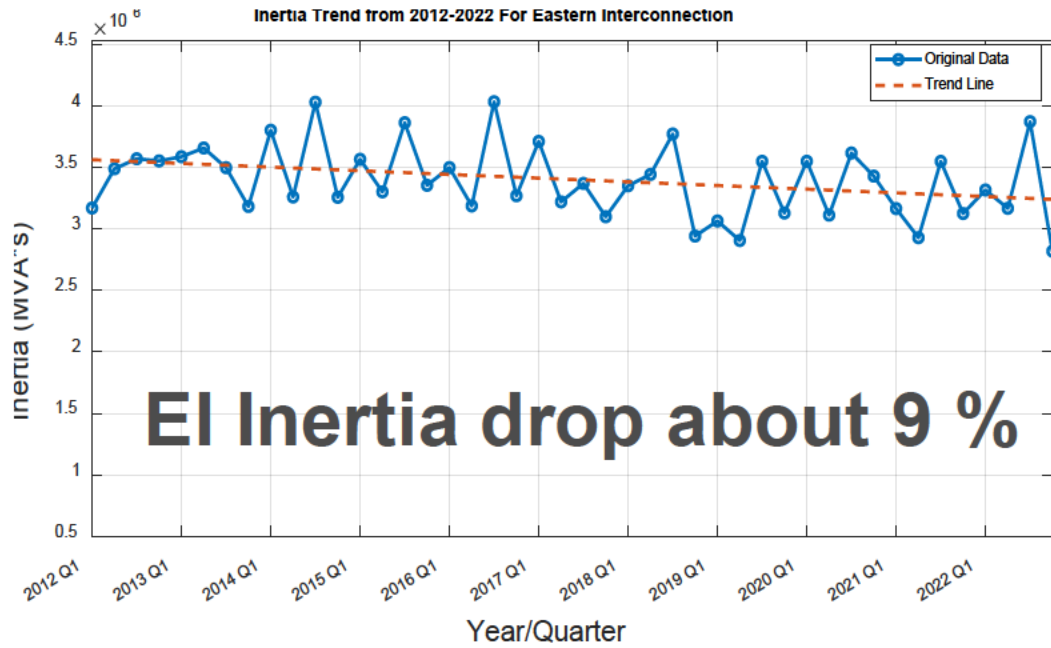
Inertia Monitoring – EI, WECC, KIUC



Helms (PG&E)
Bath County (DOM)
Racoon Mt (TVA)



EI, WECC Inertia Trend 2012-2022 (DOM, ORNL)

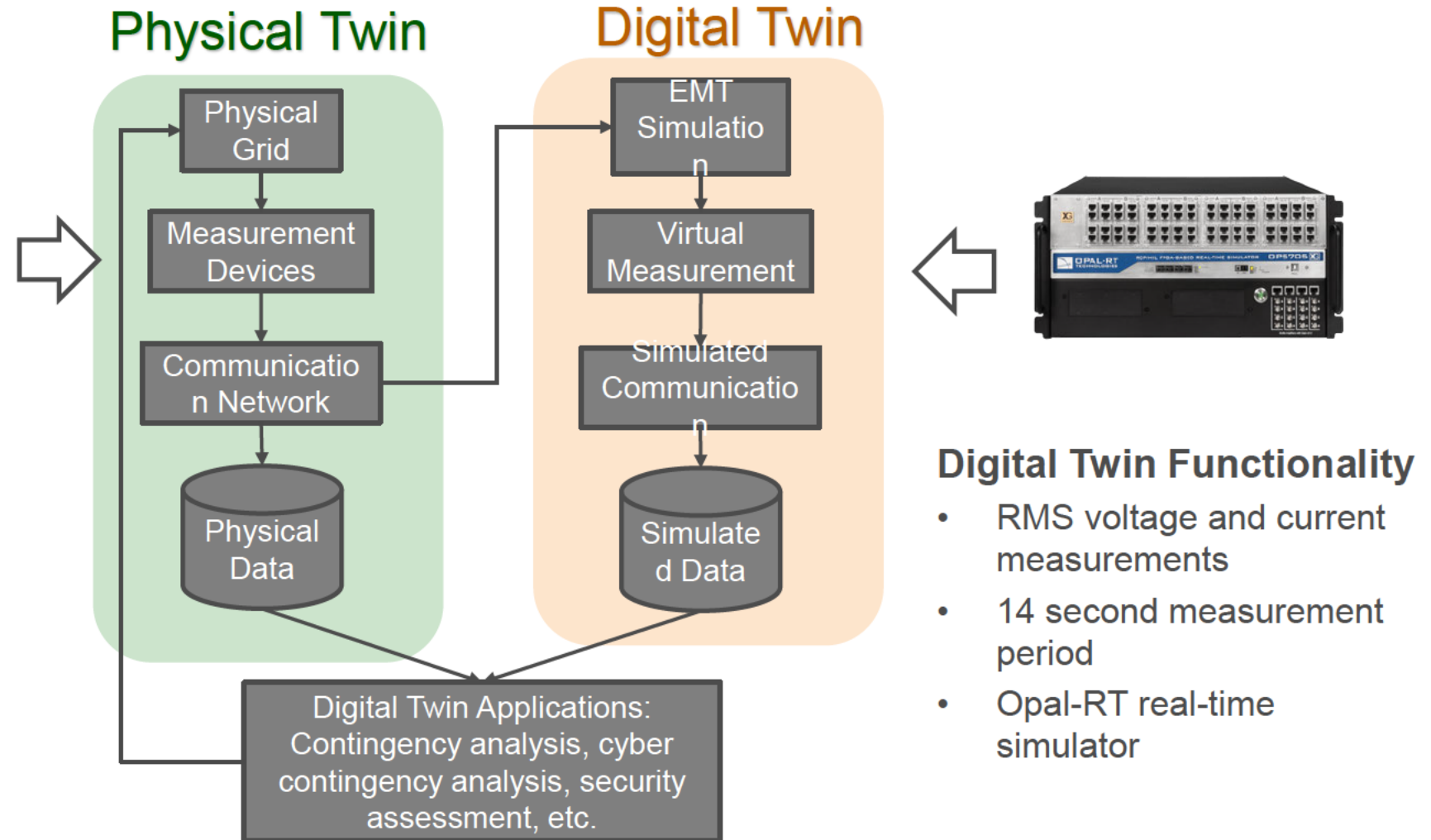


Micro Grid Digital Twin (Southern Company)



Microgrid Components

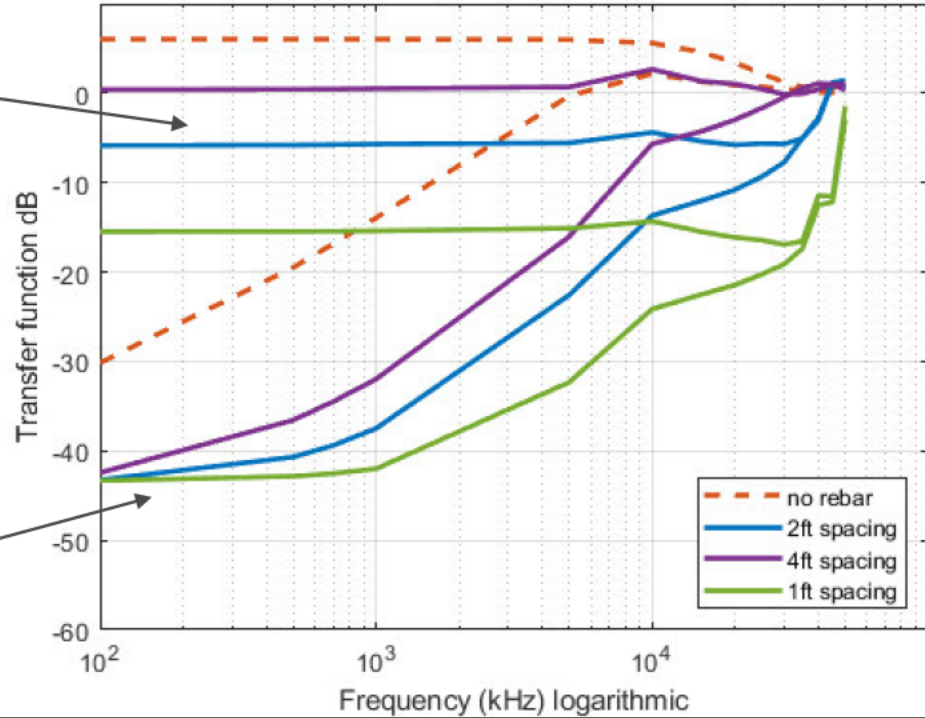
- Photovoltaic generation
- Battery energy storage
- Diesel Generation
- Residential load



Building EMP Shield Effect (ORNL)

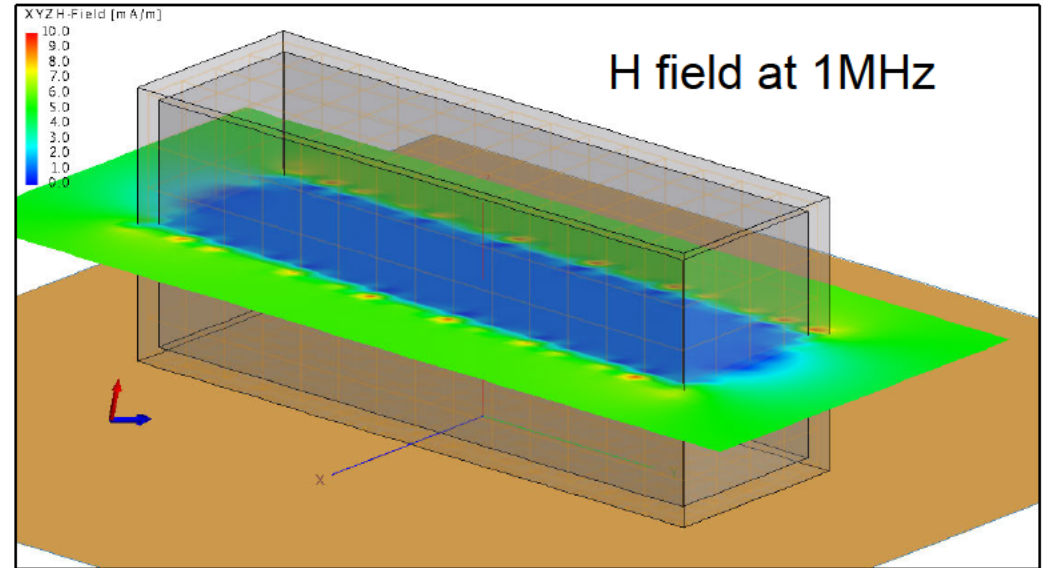
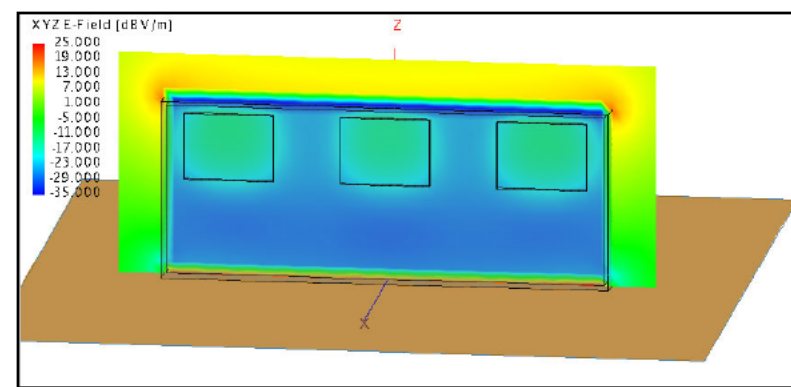
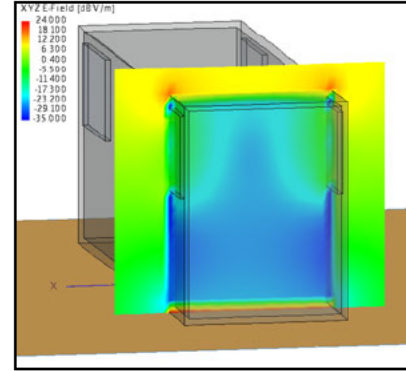
Reinforced Concrete

Transfer functions for 10m X 3m X 4m Reinforced Structure (100kHz - 50MHz)
Rebar Spacing Comparison; aoi 75deg



H field

E field



Tool Development

- Distribution three phase state estimator
- SPOT- distribution grid sensor placement tool
- Distribution Volt-Watt optimization tool
- Automatic DC to AC power flow conversion tool.
- Forced oscillation source location tool
- PSS/e to PSCAD model conversion tool
- Renewable integration tool – in development
- Regional inertia estimation tool – in development



Hector Pulgar

- UTK Associate Professor
- Research Interests: Power system stability and dynamics, energy storage systems and renewable generation.
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2023-2024 Research Projects

1. Adaptive dynamic coordination of damping controllers: Enhancing oscillation damping through a data-driven approach (funded by NSF)
2. Towards enhanced grid robustness: Augmenting grid regulating capabilities through discrete controls on emerging power technologies (funded by NSF)

Adaptive dynamic coordination of damping controllers: Enhancing oscillation damping through a data-driven approach

Project Objectives

- Adaptability to faults and operating conditions.
- Modal-based and data-driven approaches.
- IBRs are used for damping control only when the system requires them (control commitment determined promptly using activation/deactivation signals based on our data-driven scheme)

IBRs
(wind,
solar,
storage)

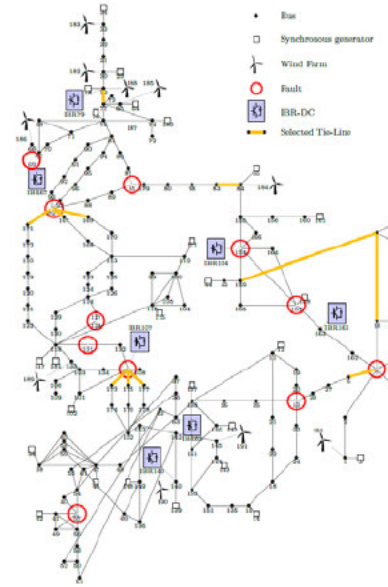
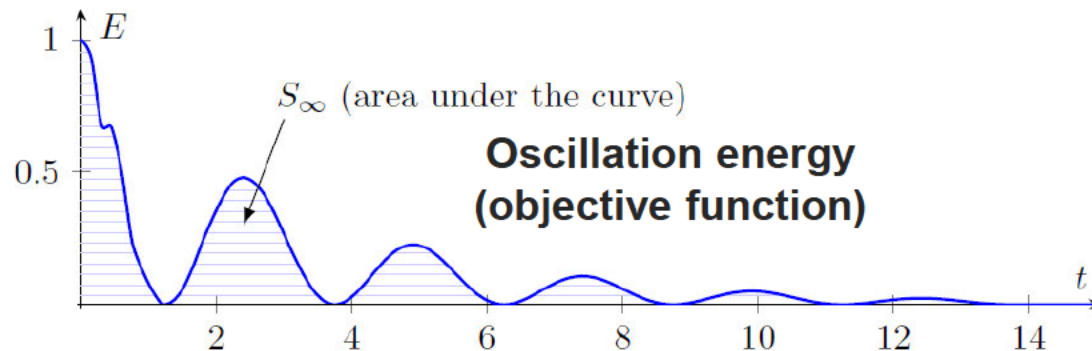
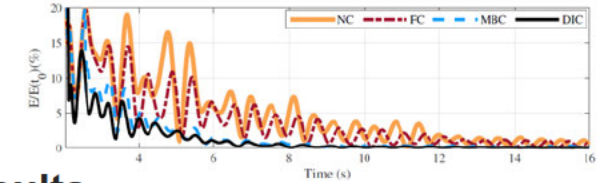


Fig. 4: 179-bus, 30-machine, 7-DC test system.



Results

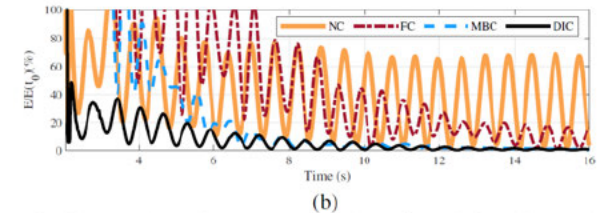
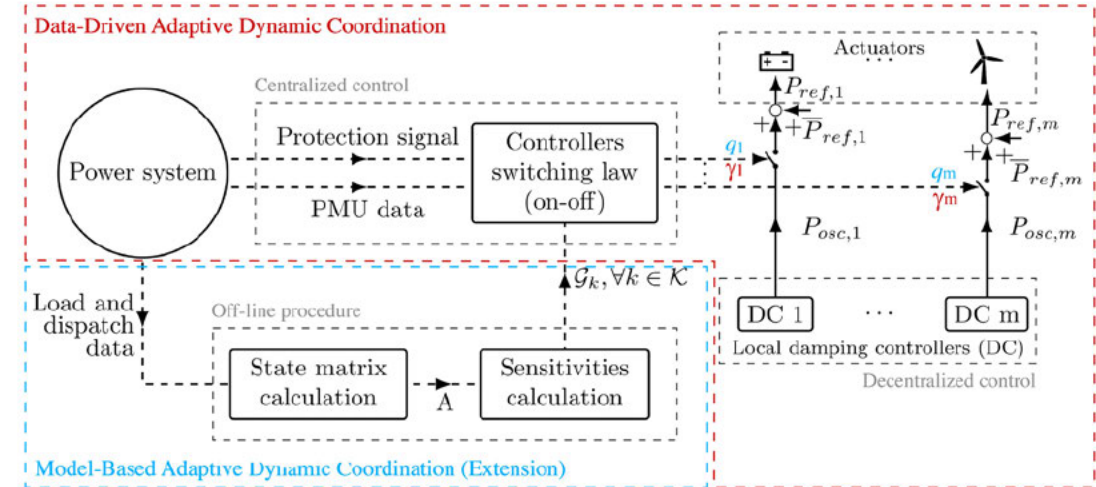
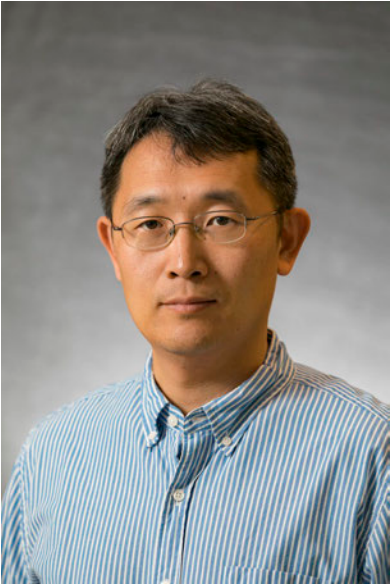


Fig. 10: Comparison between MBC and DIC for short-circuit at bus: (a) 157, and (b) 69.



Control coordination framework



Kai Sun

- **UTK Professor in Power Systems**
- **Research Interests:** Power System Dynamics, Stability and Control; Cascading Outages; Renewable Integration.
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2023-2024 Research Projects

1. A Semi-Analytical, Heterogeneous Multiscale Method for Simulation of Inverter-Dense Power Grids (NSF, ANL)
2. Intelligent Phasor-EMT Partitioning for Hybrid Simulations to Accelerate Large-scale IBR Integration Studies (SETO/NREL, ISO New England, EPRI)
3. Mobility-Energy-Coordinated Platform for Infrastructure Planning to Support AAM Aircraft Operations (NASA/New Mexico State University)

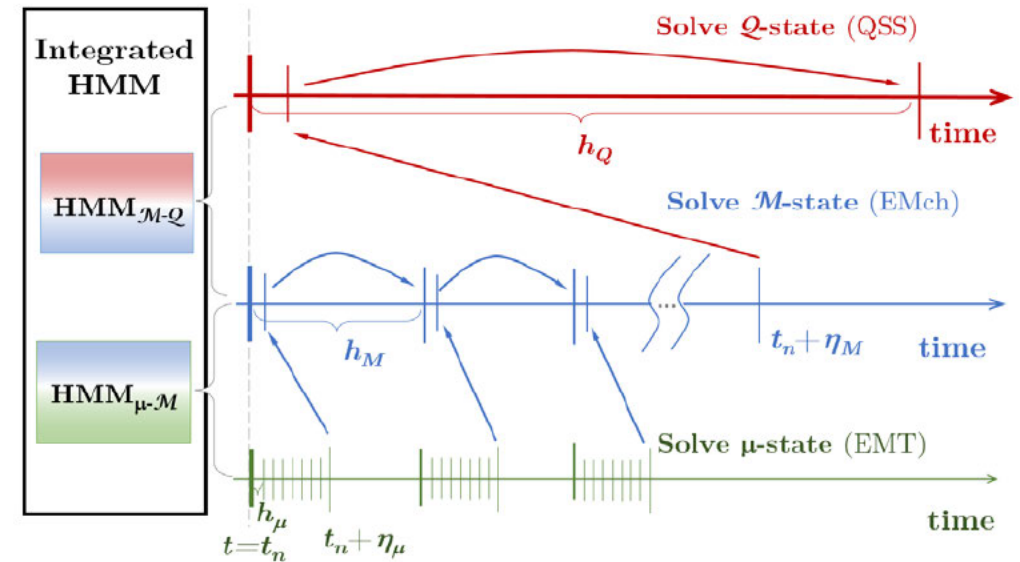


A Semi-Analytical, Heterogeneous Multiscale Method for Simulation of Inverter-Dense Power Grids

Project Objectives:

- Developing a Heterogeneous Multiscale Method (HMM) framework for automatic, case-specific model reduction on the fly of each EMT/phaser simulation.
- Developing variable-order variable-step semi-analytical solution (SAS) methods to accelerate EMT/phaser simulations.
- Targeting a 10-100x speedup of EMT simulations on large-scale grid models with 50-100% IBR penetration.

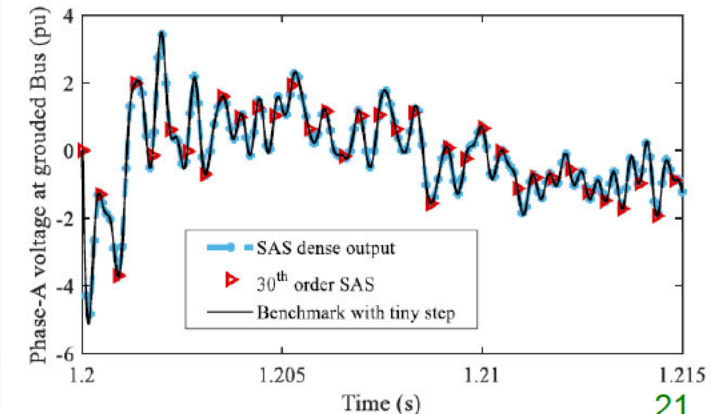
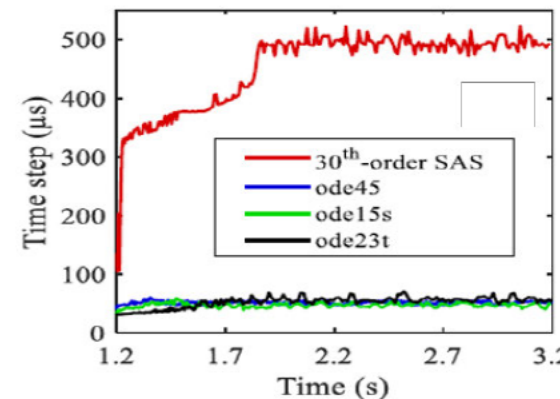
HMM framework for simulating multi-timescale (EMT, electromechanical and quasi-steady-state) grid dynamics



High-order SAS method achieves a 5-20x speedup of accurate EMT simulation by using a 10-100x stepsize.

COMPARISON OF PERFORMANCE ON A 390-BUS SYSTEM

Approach	PSCAD				SAS
Time step (μs)	5	50	75	100	534
Time cost (s)	425	42.5	28.3	21.5	98
Maximum error (pu)	0.22	2.58	3.36	3.85	7×10^{-4}
Average error ($\times 10^{-3}$ pu)	0.41	2.61	2.91	3.3	0.0012



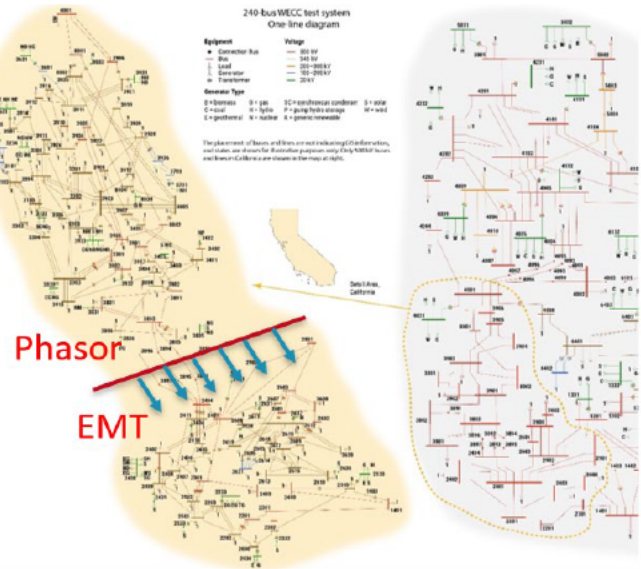


Intelligent Phasor-EMT Partitioning (I-PEP) for Hybrid Simulations to Accelerate Large-scale IBR Integration Studies

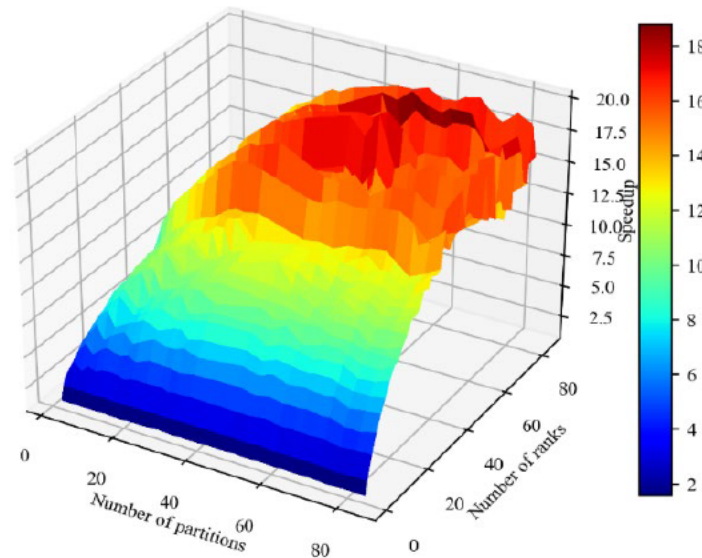
Project Objectives and Achievements:

- Intelligent determination of which portions of the grid to be simulated in EMT models while the rest in phasor models.
- Accelerated NREL's opensource simulator ParaEMT by integrating the SAS method.
- Validation of the method on realistic grid and IBR models.

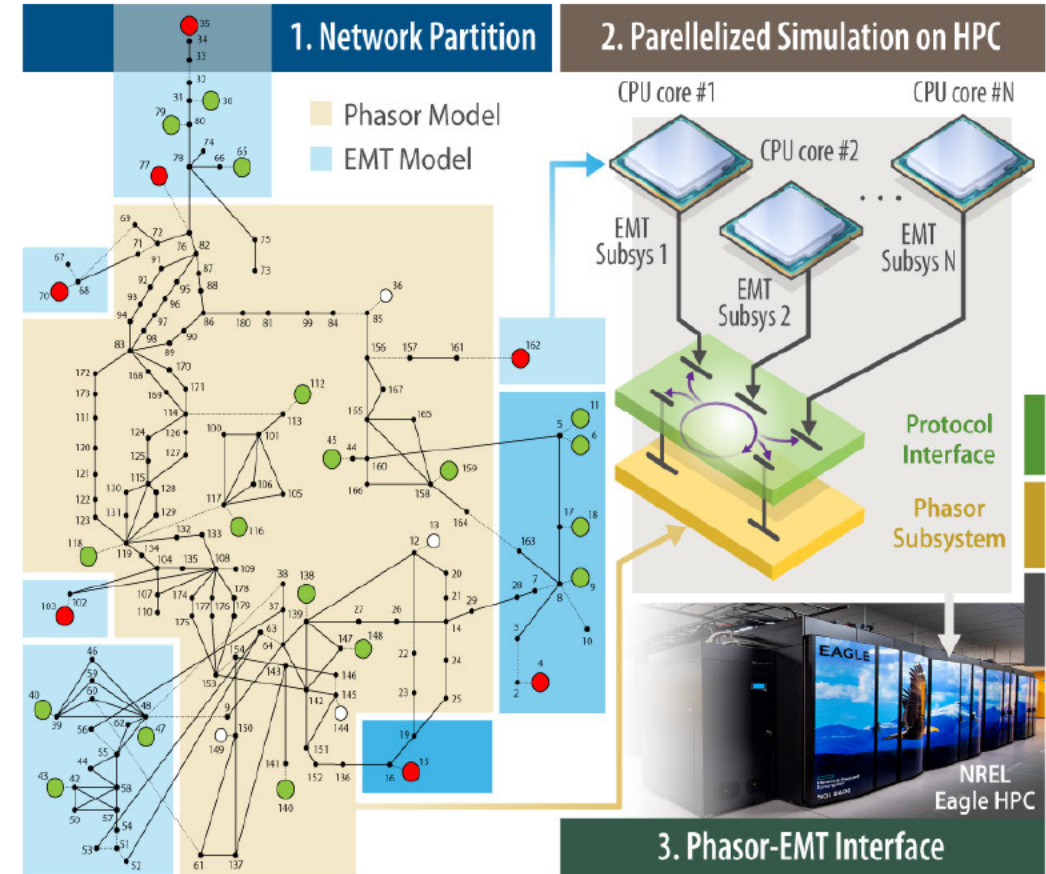
Participation Factor-based Boundary Determination



Speedup by SAS & HPC using 50 μs time step on a 10K-bus EMT model



I-PEP project overview



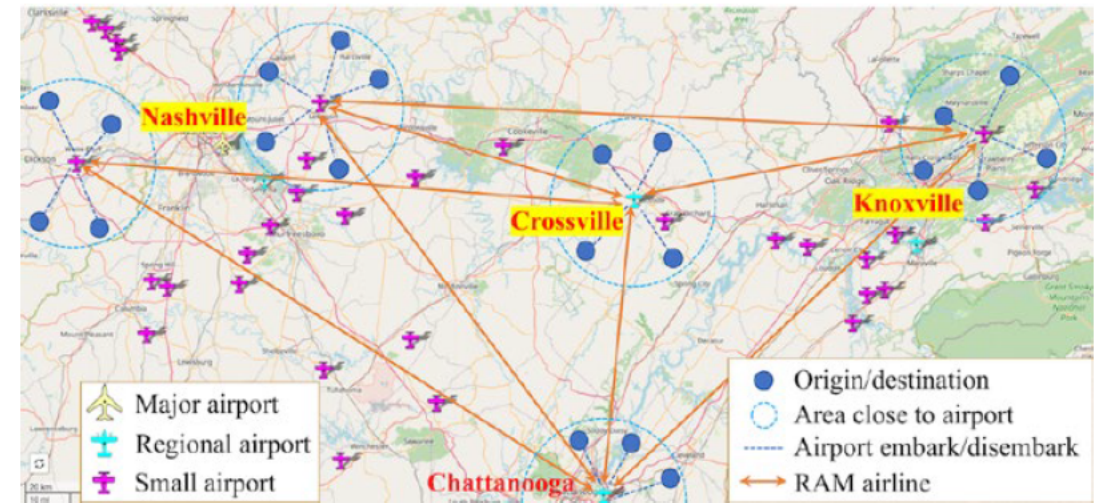


Mobility-Energy-Coordinated Platform for Infrastructure Planning to Support AAM Aircraft Operations

Project Objectives:

- Building power system testbeds to support Advanced Air Mobility (AAM) planning and operation studies.
- Evaluating the impacts of AAM operations on grid reliability and resilience based on power system reliability criteria.
- Accessing electric infrastructure readiness to support AAM aircraft charging.
- Supporting the optimal siting studies on UAM (Urban Air Mobility) and RAM (Regional Air Mobility) portals.

Concept of AAM in Tennessee and candidate locations for RAM portals





Kevin Tomsovic

- UTK Chancellor's Professor and CTI Professor
- Research Interests: control, optimization, renewable energy integration, demand response, resilience, cybersecurity.
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2023-24 Research Projects/Highlights

Recently Completed

1. WISP: Watching grid Infrastructure Stealthily through Proxies (**DOE, Raytheon**) (PI: F. Li PI; co-PI: J. Sun)
2. National Transmission Resilience and Reliability (**DOE**) – (PI: F. Li)

Recently awarded and on-going

1. CPS: Medium: Secure Constrained Machine Learning for Critical Infrastructure CPS (**NSF**) (PI: J. Sun, co-PI: H. Qi, H. Lee)
2. A Novel Approach to Mitigating Communication Failures (**NSF**) (co-PIs: S. Djouadi, F. Taousser)

A New Approach to Control under Network Communication Delays



Project goals and previous accomplishments

- A new mathematical method to estimate the maximum allowed communication delay that does not violate the stability and performance of the power system.
- Manage continuous and discrete dynamics as switching between a continuous-time subsystem (when the communication occurs without any interruption) and a discrete-time subsystem (when the communication fails) by introducing **time scales theory**.

Recent activities

- A stability criteria has been derived to estimate bounds of the communication loss duration, which guarantees the stability of the system.

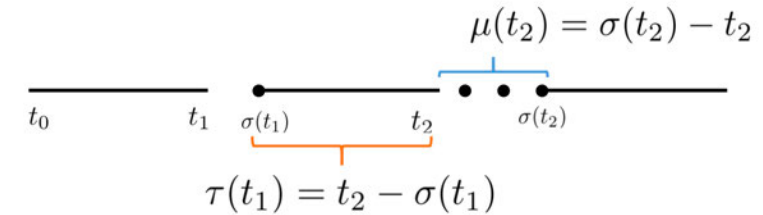
Future works

- Test stability criteria in larger system with considering communication failure.

PIs – Djouadi, Taousser and Tomsovic (PI)

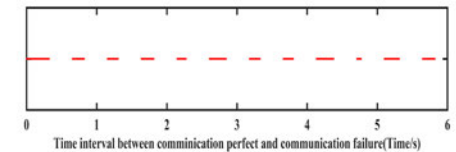
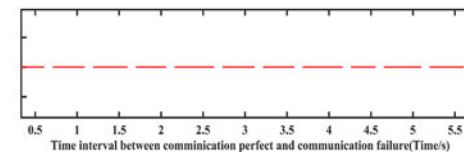
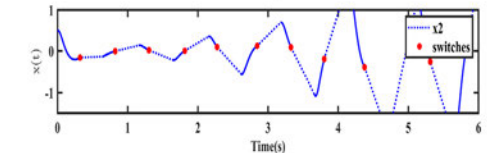
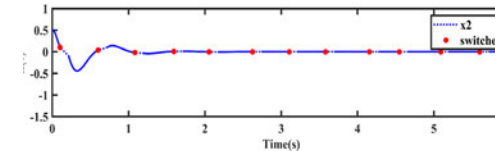
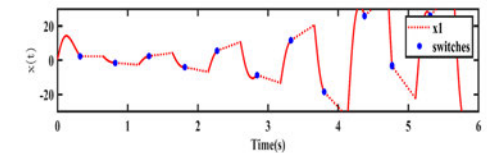
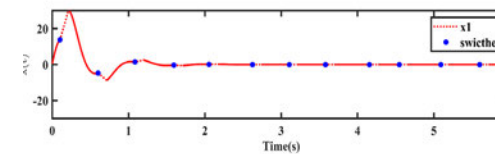
Students: Yichao Wang

Time scales



Switched system

$$x^\Delta(t) = \begin{cases} (A + BK)x(t), & t \in \cup_{i=0}^{\infty} [\sigma(t_i), t_{i+1}) \\ \left(\frac{e^{A\mu(t)} - I}{\mu(t)} \right) (I + A^{-1}BK) x(t), & t \in \cup_{i=0}^{\infty} \{t_{i+1}\} \end{cases}$$



Exploring Physical-Based Constraints in Forecasting: A Defense Mechanism Against Cyberattack



Project goals and previous accomplishments

- Concern with Cyber attacks in machine learning systems
- Physical-based constraints can provide obstacles that makes attacks more difficult.
- Attacker needs to meet the constraints imposed by the physical/topology of system and evade any built-in detection mechanisms in the system.

Recent activities

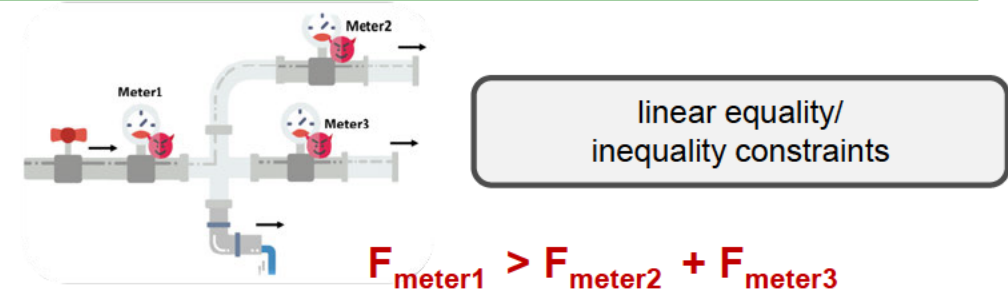
- Proposed a framework to spatially investigate STLF for a defense mechanism (also for traffic systems)
- Applied similarity measures to explore physical-based constraint.
- Outperformed of SAX method, showing more sensitivity to false data injection.

Future works

- Test stability criteria in larger system with considering communication failure.

Pis – Han, Qi, Sun (PI) and Tomsovic

Students: Mojtaba Dezvarei, Farhin Farhad Riya, Ony Hoque, Diyi Liu, Lanmin Liu, Quan Zhou



Water flow measurement

Spatial correlations

- Correlation-based distance: $d_{COR}(X, Y) = \sqrt{2(1 - COR(X, Y))}$
- Periodogram-based distance: $d_p(X, Y) = \sqrt{\sum_{j=1}^{\lfloor \frac{N}{2} \rfloor} [\rho_x(\omega_j) - \rho_y(\omega_j)]^2}$
- Autocorrelation-based distance: $d_{ACF}(X, Y) = \sqrt{(\hat{\rho}_{X_T} - \hat{\rho}_{Y_T})^T \Omega (\hat{\rho}_{X_T} - \hat{\rho}_{Y_T})}$
- Symbolic representation SAX: Time series transforming into a string.
- Euclidean-based distance: $d_{EUC}(X, Y) = \sqrt{\sum_{i=0}^{N-1} (x_i - y_i)^2}$