

# Letters

## Full Integration of On-Board Charger, Auxiliary Power Module, and Wireless Charger for Electric Vehicles Using Multipurpose Magnetic Couplers

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**Abstract**—To further improve the system integration and convenience of the battery charging system for electric vehicles, this letter proposed a multipurpose magnetic coupler-based charging solution that integrates bidirectional on-board charger (OBC), wireless power transfer (WPT), and an auxiliary power module (APM). The proposed solution presents multiple highlights: 1) the first exhibited solution to integrate OBC, WPT, and APM in one unit; 2) magnetic integration that uses a multiwinding WPT pad to eliminate the main transformer of OBC and APM; and 3) topological integration that saves multiple active and passive devices. This letter includes a description of the system topology, operation principles of individual charging modes, a novel magnetic coupler, and the design methodology. Finally, a prototype was constructed and different charging modes were tested to validate the proposed design.

**Index Terms**—Battery chargers, electric vehicles (EVs), integrated magnetics, multiport converters, wireless power transfer (WPT).

### I. INTRODUCTION

ADVANCED charging systems are essential for promoting the adoption of electric vehicles (EVs), as they help to alleviate mileage anxiety and enhance the user experience [1]. To offer more convenience than conductive charging, the automotive industry is also exploring wireless power transfer (WPT)-based charging solutions, which provide a hassle-free charging experience but are usually expensive with limited

charging power. EVs equipped with both on-board charger (OBC) and WPT allow users to select either charging speed or charging convenience but could be bulky and costly.

In addition, the auxiliary power module (APM) is an inevitable on-board unit that charges the 12 V battery to support low voltage (LV) loads on vehicles. Usually, OBC, WPT, and APM are designed, manufactured, and installed separately. This requires a complex cooling system, complicated assembly, and eventually high cost and large size. To improve the power density and reduce the cost of charging units, different levels of the integration of charging units have been proposed in past decades [2], [3], [4], [5], [6], [7].

Mechanical integration is a basic and low-level integration, which can help to increase the system's compactness, however, only saves the cost of the enclosure and cooling system. High-level topological and magnetical integration is much more preferred for next-generation integrated charging systems. In [3], a dual-transformer topology is utilized to integrate OBC and APM by sharing the rectifier. The integration is further improved by using a three-port transformer to build a voltage-fed (VF) triple-active bridge [4] or a current-fed (CF) triple-active bridge [5]. Similarly, the integration of OBC and WPT has been realized by sharing an active bridge [6]. Recently, high-level integration of OBC and WPT with the shared full bridge and magnetic components is presented in [7]. However, using the aforementioned integration approaches, at least two separate units are still needed for EVs that intend to offer both conductive and wireless charging methods at the same time.

To achieve a higher-level integration of the EV charging system, a full integration of bidirectional OBC, WPT, and APM using a multipurpose magnetic coupler is proposed in this letter, which is inspired by previously successful integration cases, i.e., OBC+APM and OBC+WPT. Figs. 1 and 2 show the block diagram of the conventional standalone solution and the proposed integrated solution, respectively. Compared with the standalone solution and the previous integrated chargers, the proposed integration method offers several benefits: 1) integration of OBC, WPT, and APM by one compact unit

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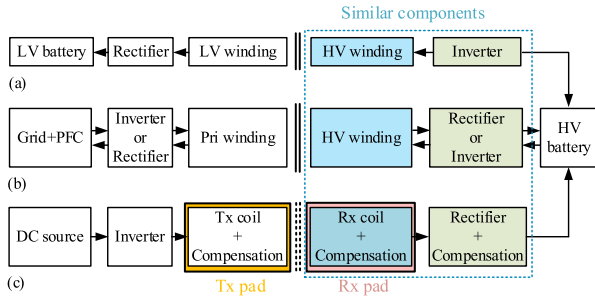


Fig. 1. Block diagram of the EV charging system with standalone OBC, WPT, and APM units. (a) APM. (b) OBC. (c) WPT.

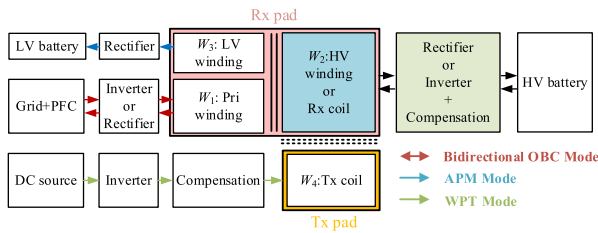


Fig. 2. Block diagram of the proposed fully integrated EV charging system with the OBC, APM, and WPT functions using multipurpose magnetic coupler and shared circuit components.

through a simple multipurpose magnetic coupler and 2) elimination of two HV active bridges, two conventional transformers and other related active and passive components in the standalone units. The EV charging system can then achieve higher power density and lower cost.

## II. PROPOSED INTEGRATION METHOD

### A. Topology

The proposed integrated EV charger is shown in Fig. 3. Coils  $W_1$ – $W_4$  form a multipurpose magnetic coupler, where  $W_2$  is shared and can serve as the secondary winding of the OBC, the receiver (Rx) coil of the WPT, and the primary winding of the APM. To connect to the 3- $\Phi$  grid with up to 480 Vac line-line voltage and generate the dc bus voltage up to 800 V, a multilevel topology is adopted aiming at using lower-voltage power switches. Here,  $Q_{a1}$ – $Q_{a6}$  form a three-level (3-L) active-neutral-point-clamp phase leg, and 3- $\Phi$  legs form the complete ac–dc stage.  $P_1$ – $P_4$ ,  $S_{11}$ – $S_{14}$ , and  $S_{31}$ – $S_{34}$  form a triple-active-bridge (TAB) converter with a VF port at the HV side and a CF port at the LV side.  $S_{21}$ – $S_{24}$  form a 3-L dc/dc converter at HV side, which connects to the 400 V/800 V battery.  $S_{41}$ – $S_{44}$  form the WPT inverter.  $C_b$  is the dc blocking cap,  $L_{o1}$  is the inductor of the dc/dc converter for the OBC and the WPT, and  $L_{o2}$ – $L_{o3}$  is the coupled filter inductor for the APM. The inductor-capacitor-capacitor-series compensation topology, which consists of  $L_{r1}$ ,  $C_{r1}$ ,  $C_{r2}$ , and  $C_{r3}$ , is adopted for WPT.

### B. Operation Mode

When the system works in the OBC mode or the APM mode, The operation frequency is much higher than the resonant frequency of the WPT mode, thus the impedance of  $C_b$  and  $C_{r3}$

can be ignored, and the charger is operated as a TAB converter. The three-port transformer consists of closely coupled  $W_1$ ,  $W_2$ , and  $W_3$ . Phase-shift modulation and pulsewidth modulation can be used to decouple the power flow and modulate the output power [5], [8]. The output power can be regulated by TAB and the following dc/dc stage.

In WPT mode, the converter is working at the resonant frequency, which is calculated as follows:

$$2\pi f_{\text{WPT}} = \frac{1}{\sqrt{L_2 C_{r3}}} = \frac{1}{\sqrt{L_{r1} C_{r2}}} = \frac{1}{\sqrt{L_4 \frac{C_{r1} C_{r2}}{C_{r1} + C_{r2}}}}. \quad (1)$$

The zero-current-detection-based synchronized rectifier control is utilized at the Rx side to improve efficiency [9]. To avoid impacts of the induced voltage on  $W_2$  and  $W_3$ , relay  $K_{pri}$  and  $K_{lv}$  will be open in the WPT mode WPT.

## III. MAGNETIC COUPLER DESIGN

The structure of the proposed magnetic coupler is shown in Fig. 4, with coils  $W_1$ ,  $W_2$ , and  $W_3$  forming a strongly coupled three-winding transformer for OBC and APM modes, while  $W_2$  is loosely coupled with  $W_4$  for the WPT mode.

The design method of the proposed magnetic coupler is summarized in Fig. 5. Because the magnetic coupler is derived from the conventional WPT pad, the design procedure is: 1) WPT Rx and Tx coil,  $W_2$  and  $W_4$ , 2) OBC primary coil,  $W_1$ , and 3) LV secondary coil,  $W_3$ . The basic design principles are introduced as follows.

As of  $W_2$  and  $W_4$  for the WPT, higher coupling coefficient  $k$  and quality factor  $Q$  are always preferred when designing Rx and transmitter (Tx) coils for high efficiency and high power. The main factors that affect  $k$  and  $Q$  of coils are: 1) Coil size, 2) Coil topology, 3) Coil turns, and 4) Materials of the ferrite tiles and wires. Considering the flexibility of integrating other coils in the Rx pad, the most common circular planar topology is chosen and the outer diameter is set to 500 mm to transfer 6.6 kW efficiently with 200 mm vertical distance [10], [11].

To integrate  $W_1$  and  $W_3$  into the Rx pad, all windings are designed to the same planar form as  $W_2$ . For  $W_1$  and  $W_3$ , the main design variables are the leakage inductance and the turn ratio. Considering the rated voltage range at the primary side, HV side, and LV side is 300–400 V, 250–450 V, and 20–50 V, respectively, the turn ratio of  $W_1$ ,  $W_2$ , and  $W_3$  is set to 14:14:1. To fully utilize the space and ferrite tiles of the Rx pad and ensure strong coupling, the interleaved structure is applied, as shown in Fig. 4.

Different from the conventional transformer, adding one single LV turn will lead to low coupling between coils, and thick wire is needed considering the high-current capability. To reduce the resistance of the LV coil and achieve strong coupling, a multiturn-paralleling structure is used.

Based on the selected Litz wires, the arrangement, i.e., vertical and horizontal arrangements, and the position of LV coil as shown in Fig. 6, are optimized. The paralleling turn number is mainly determined by the RMS current of the LV side. However, too few turns can lead to weak coupling between  $W_2$  and  $W_3$ . For the prototype, eight paralleling turns are used for the LV coil.

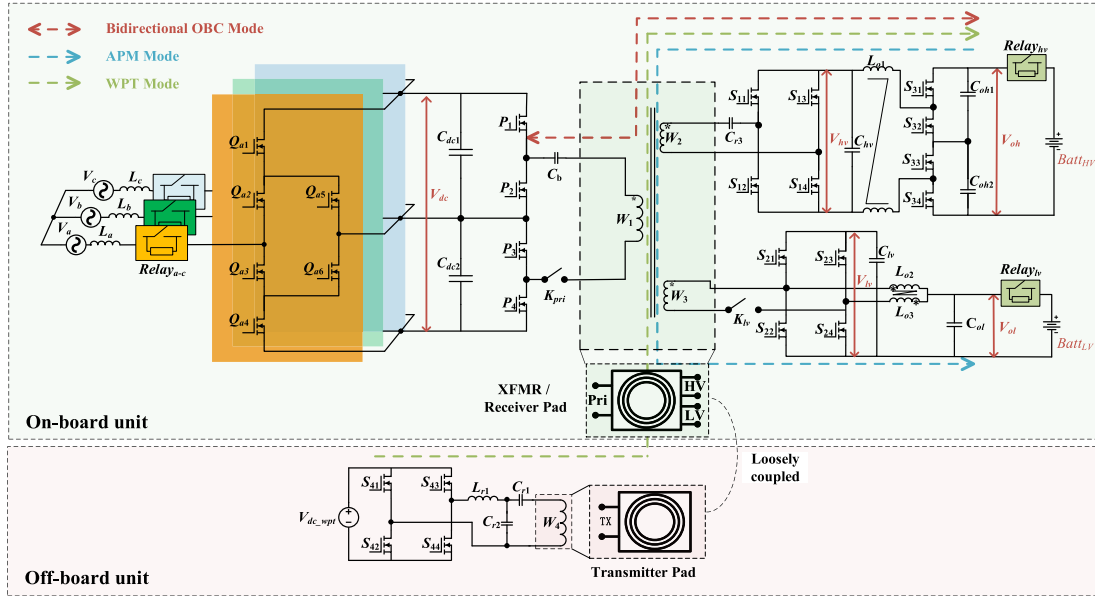


Fig. 3. Proposed topology of the fully integrated EV charger.

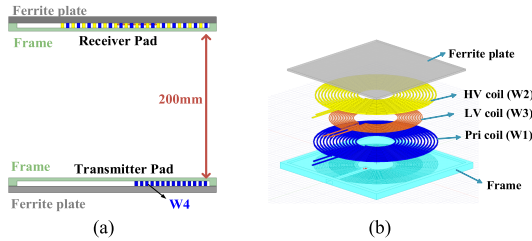


Fig. 4. Charging pads structure. (a) Section view of two pads. (b) Explosive view of the Rx pad.

The simulated coupling coefficient between  $W_2$  and  $W_3$ , and the leakage inductance at the LV side are conducted for optimization purpose, as shown in Fig. 7. It shows that the horizontal arrangement has the higher coupling coefficient and the lower leakage inductance. Thereby, the case shown in Fig. 6(d) is used for the prototype.

The advantages of such a design are summarized in the following.

- 1) The design methodology of conventional WPT coils can still be referenced and utilized.
- 2) The structure is simple, and the size and thickness of the pad are not increased with three coils integrated in.
- 3) Strong coupling of  $W_1$ ,  $W_2$ , and  $W_3$  can be ensured, and core loss could be much smaller than using the conventional transformer, benefiting from the larger ferrite tile size.

#### IV. SIMULATION AND EXPERIMENTAL VALIDATION

As shown in Fig. 8, the magnetic coupler is manufactured. The specifications of the proposed magnetic coupler are listed in Table I. The measured parameters of the coupler are shown in

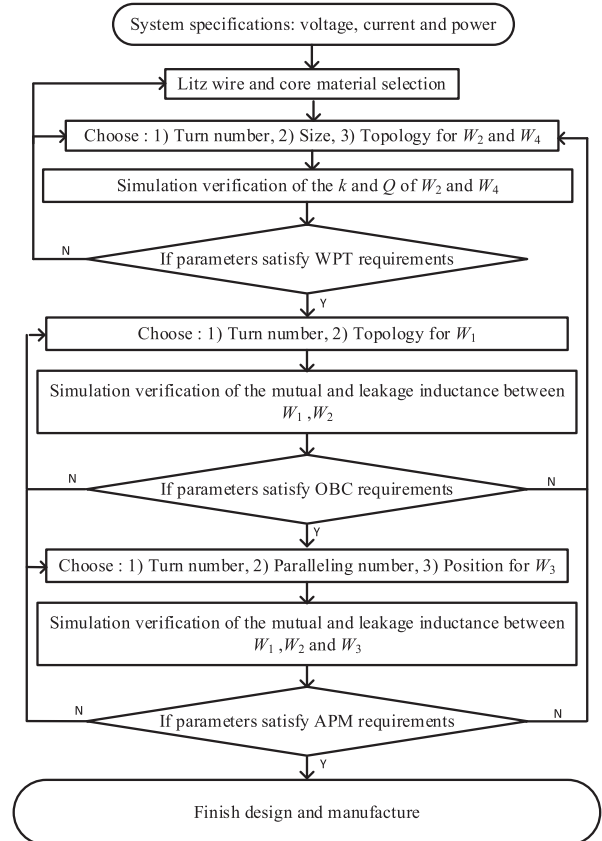


Fig. 5. Design method of the proposed magnetic coupler.

Table II, where  $k_{12}$ ,  $k_{23}$ , and  $k_{24}$  are the coupling coefficients of the respective coils.  $k_{24}$  is measured with a 200 mm air gap between two pads. Large  $k_{12}$  reflects the strong coupling resulting



Fig. 6. Examples of the LV coils with different arrangements and positions. (a) Vertical, LV position = 0. (b) Vertical, LV position = 10. (c) Horizontal, LV position = 0. (d) Horizontal, LV position = 10.

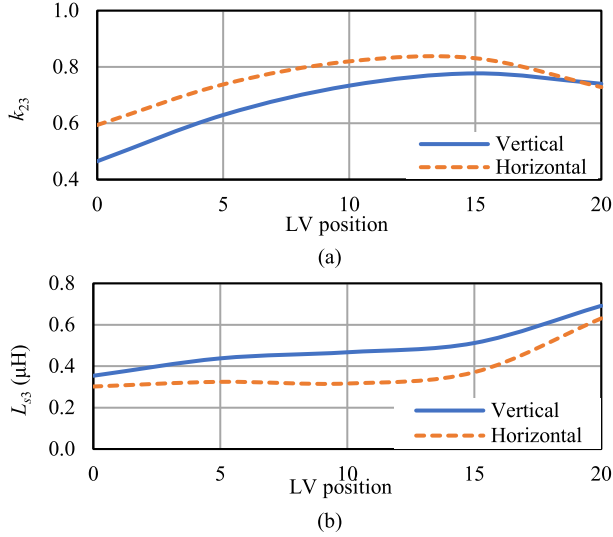


Fig. 7. Simulation results based on the eight-turn paralleled LV coil. (a) Coupling coefficient between HV and LV coils. (b) Leakage inductance on LV side.

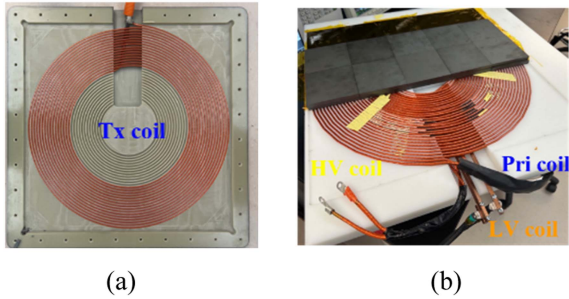


Fig. 8. Manufactured pads. (a) Tx pad. (b) Rx pad.

TABLE I  
SPECIFICATIONS OF THE MAGNETIC COUPLER

Coil	Pri coil ( $W_1$ )	HV coil ( $W_2$ )	Tx coil ( $W_3$ )	LV coil ( $W_4$ )
Litz wire	NLD3300/42SPIT (New England wire)			NELD1710/42SPSN (New England wire)
Size (mm)	5.89 × 3.56			∅ 2.87
Equiv. AWG	4			12
Outer diameter (mm)	480	464	480	176.8
Inner diameter (mm)	69.5	63.1	145.8	132.9
Magnetic tile	FPL100/100/4-BH1T			

TABLE II  
PARAMETERS OF THE MAGNETIC COUPLER

Parameter	$L_1$	$L_2$	$L_3$	$L_4$	$L_{s1}$
Value	90.3 $\mu\text{H}$	86 $\mu\text{H}$	1.47 $\mu\text{H}$	212 $\mu\text{H}$	5.23 $\mu\text{H}$
Parameter	$L_{s2}$	$L_{s3}$	$k_{12}$	$k_{23}$	$k_{24}$
Value	1.58 $\mu\text{H}$	0.31 $\mu\text{H}$	0.95	0.66	0.133

TABLE III  
SYSTEM SPECIFICATIONS

Parameter	$f_{OBC}$	$f_{APM}$	$f_{WPT}$	$L_{F1}$	$C_{F1}$	$C_{F2}$
Value	240 kHz	100 kHz	42.5 kHz	63.3 $\mu\text{H}$	85 nF	250 nF
Parameter	$C_{F3}$	$V_{ac}$	$V_{dcbus}$	$V_{dc WPT}$	$V_{bat HV}$	$V_{bat LV}$
Value	176 nF	380 V	650 V	400 V	350 V	12 V

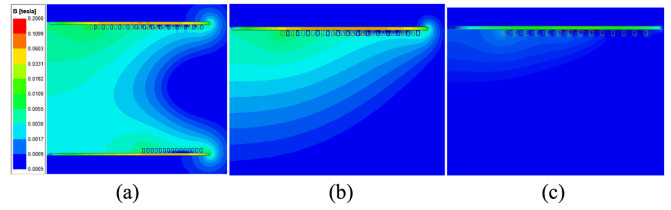


Fig. 9. Simulated flux density distribution. (a) WPT. (b) OBC. (c) APM.

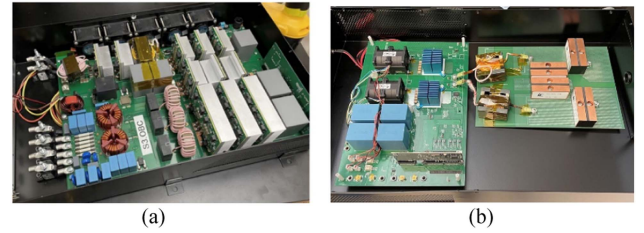


Fig. 10. Experimental prototype. (a) On-board unit. (b) Off-board unit.

from the interleaved design.  $k_{12}$  and  $k_{24}$  are also acceptable for APM and WPT systems. The system specifications are given in Table III.

The simulated magnetic field in the tiles and air space at OBC, APM, and WPT modes is shown in Fig. 9. Maximum magnetic flux densities in the ferrite tiles are 0.08 T, 0.012 T, and 0.013 T for 6.6 kW WPT, 6.6 kW OBC, and 1.5 kW APM, respectively. The simulations verify that, in addition to the WPT function, the ferrite tiles in the proposed magnetic coupler also satisfy the requirement of OBC and APM modes. No additional cores or separate transformers are needed, which is aligned with the analysis in Section III and lower core loss in the OBC and APM mode can be expected.

A prototype, including the on-board unit and off-board unit, is built, as shown in Fig. 10. All individual functions are verified by experiments, including 10.3 kW OBC, 6.6 kW WPT, 3.7 kW vehicle-to-load (V2L), and 800 W APM. A battery emulator is used as the load for the OBC, WPT, and APM test, and a fixed three-phase resistive load of 22  $\Omega$  on each phase is used for the V2L mode. The key waveforms are shown in Fig. 11, and the measured efficiency curves are shown in Fig. 12. Peak efficiency of 96.1%, 92%, and 92% are achieved for bidirectional



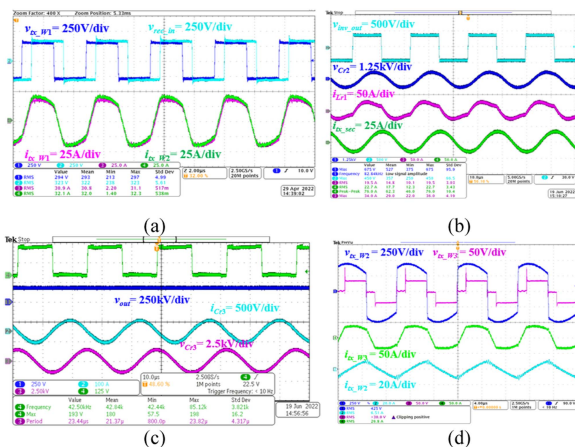


Fig. 11. Key waveforms. (a) OBC. (b) WPT inverter. (c) WPT secondary sync rectifier. (d) APM mode.

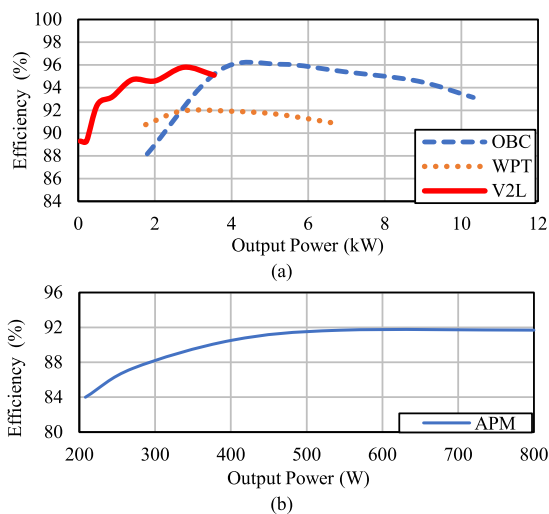


Fig. 12. Efficiency of different modes. (a) OBC, WPT, and V2L. (b) APM.

OBC, WPT, and APM, respectively. Although, there is still further improvement to make in future work, e.g., increasing the efficiency of WPT and OBC at the light load due to hard switching, nevertheless, all functionalities are evaluated by the experiments, and the volume of 9.92 L is achieved by the on-board unit of the proposed integrated charger. A comparison between the standalone units and the proposed integrated charger is given in Table IV. Based on the average power density of the reference design, the total volume of the standalone OBC+APM+WPT having a similar power capability is estimated to be > 12 L. Therefore, the volume reduction of over 2 L is achieved and a smaller pad is used compared with the references.

## V. CONCLUSION

This letter introduces a novel multipurpose magnetic coupler-based fully integrated charger capable of offering WPT, bidirectional OBC, and APM functionalities within a single unit. By integrating three coils into the Rx pad, it not only serves as

TABLE IV

COMPARISON OF THE STANDALONE UNITS AND THE PROPOSED INTEGRATED CHARGER

	OBC [12],[13],[14]	APM [15],[16],[17]	WPT [18],[19],[20]	This work
Average power density (kW/L)	1.29	0.45	–	1.85
Average pad size (m <sup>2</sup> )	N/A	N/A	0.42	0.2
Total volume of 11kW OBC+ 0.8kW APM + 6.6kW WPT	> 12 L			9.92 L

the WPT mode's Rx pad but also functions as the three-winding transformer for the TAB converter in both OBC and APM modes. Despite its multifunctionality, the Rx pad retains a simple and compact design. When compared with standalone solutions, the proposed integrated system eliminates the need for two traditional transformers and two active bridges. This results in a >2L volume reduction and corresponding cost decreases. Comprehensive evaluations of the proposed functionalities were conducted, with experimental results affirming the efficacy of this integrated approach.

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